

μ BooNE

Machine Learning Applications
in
MicroBooNE
LArTPC Detector

Fermilab Machine Learning Group Meeting

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Massachusetts
Institute of
Technology



NEVIS LABORATORIES
COLUMBIA UNIVERSITY

Machine Learning Applications in **MicroBooNE** **LArTPC Detector**

Fermilab Machine Learning Group Meeting

Outline

- **Machine learning apps in MicroBooNE**
- LArTPC image data + challenges
- Convolutional Neural Networks in MicroBooNE
- Summary

Machine Learning Applications in UB

Boosted Decision Tree

- Used for low energy (>40 MeV) NC1P search
- Input: reconstructed parameters (length, angle, etc...)
- Analysis details available in [UB public note page](#)

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Convolutional Neural Networks

- Demonstrated with LArTPC in [1st UB publication](#)
- Usage being developed for multiple purpose
 - Reconstruction: vertex detection, PID, clustering...
 - Analysis: final state classifier
- Input: either raw data (waveforms) or reconstruction

Machine Learning Applications in UB

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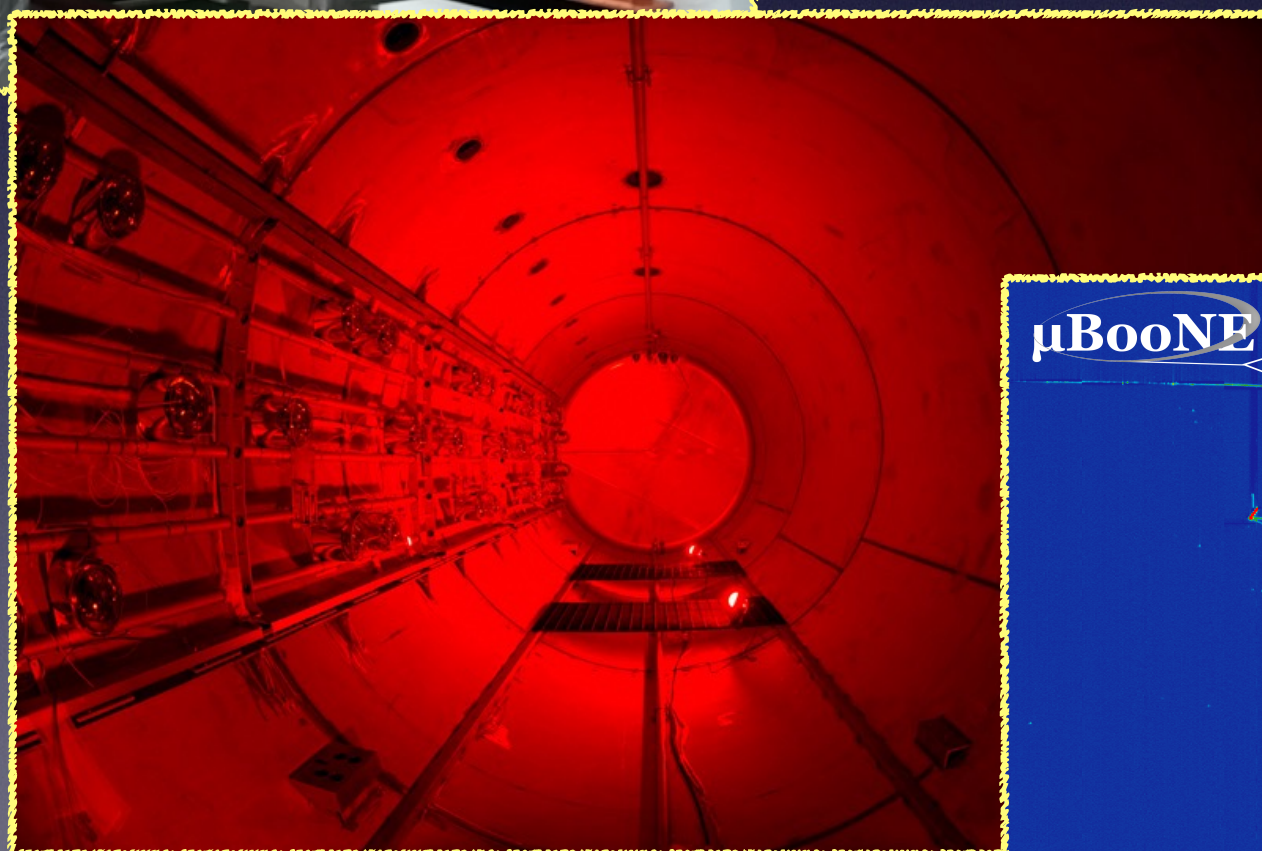
Convolutional Neural Networks

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My focus today



MicroBooNE LArTPC Image Data



MicroBooNE!



MicroBooNE

Physics goal: understand excess ν_e observed by MiniBooNE

- Must be able to identify ν_e events at low energy (100 to 600 MeV)

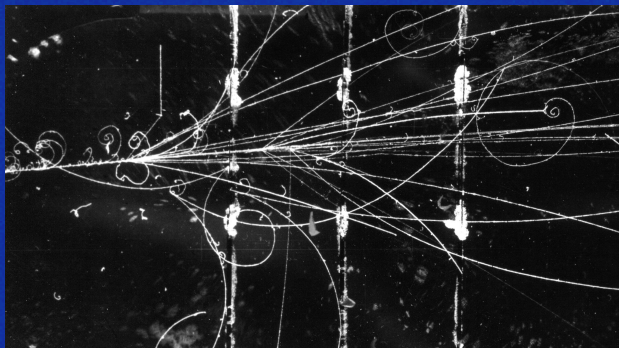
... **and more:**

- LArTPC R&D, event reconstruction, ν -Ar x-section & nuclear effects

LArTPC: Particle Imaging Machine

μ BooNE

ν_μ →



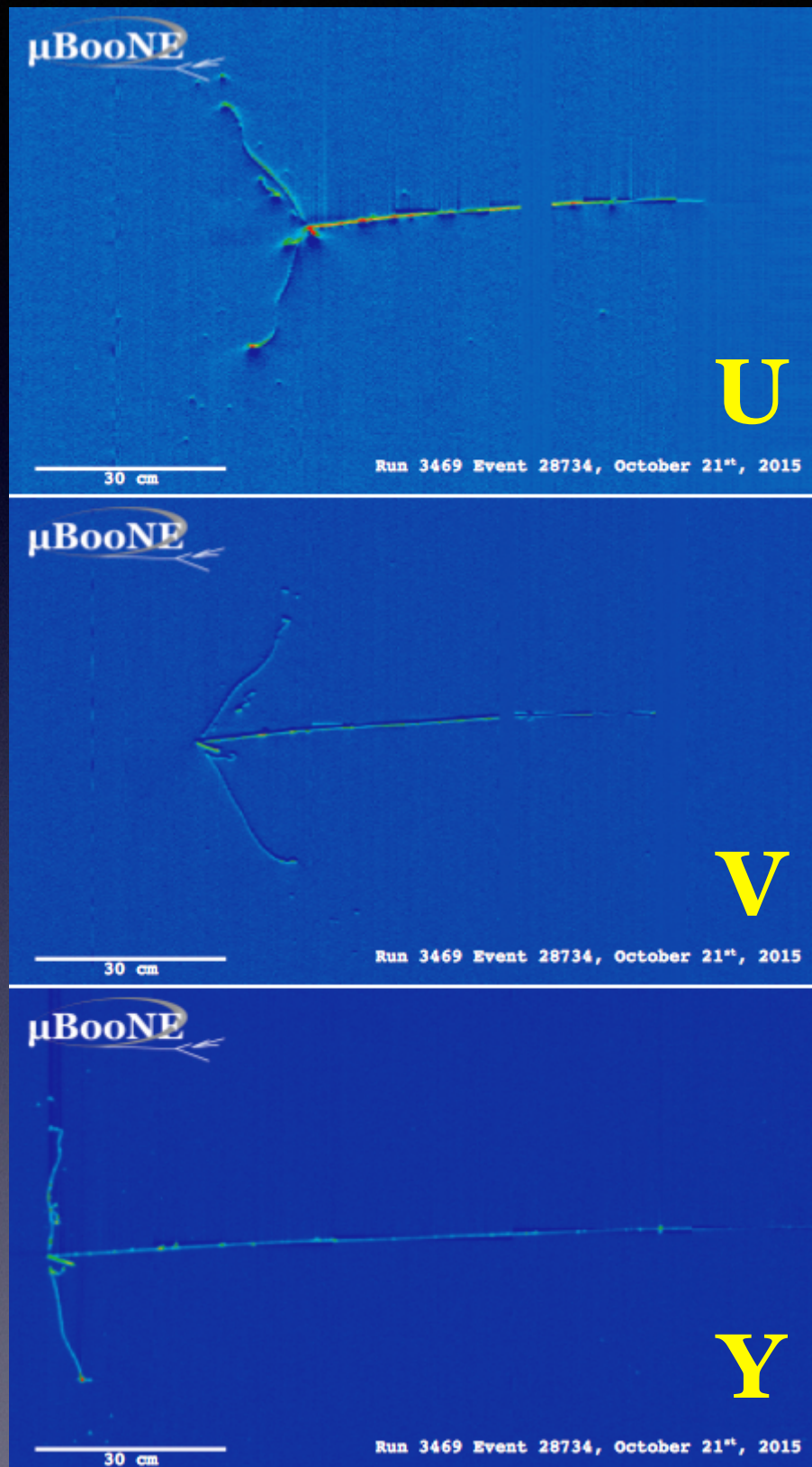
Bubble Chamber

Liquid Argon Time Projection Chamber

- Digitized bubble Chamber-like images
- Hi-resolution (~ 3 mm/px) 2D views + calorimetric information

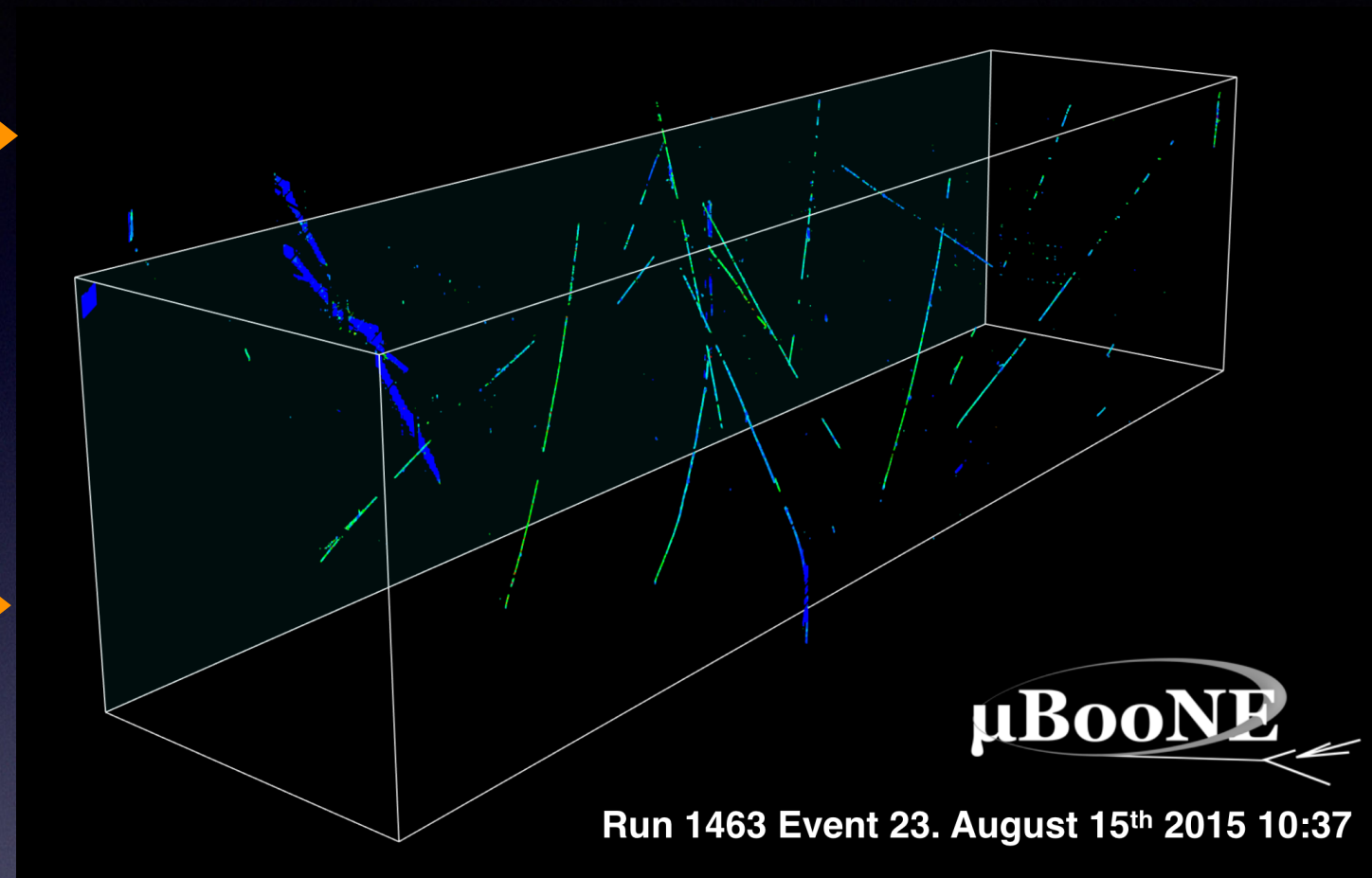
2015

LArTPC: Particle Imaging Machine



Three 2D Views

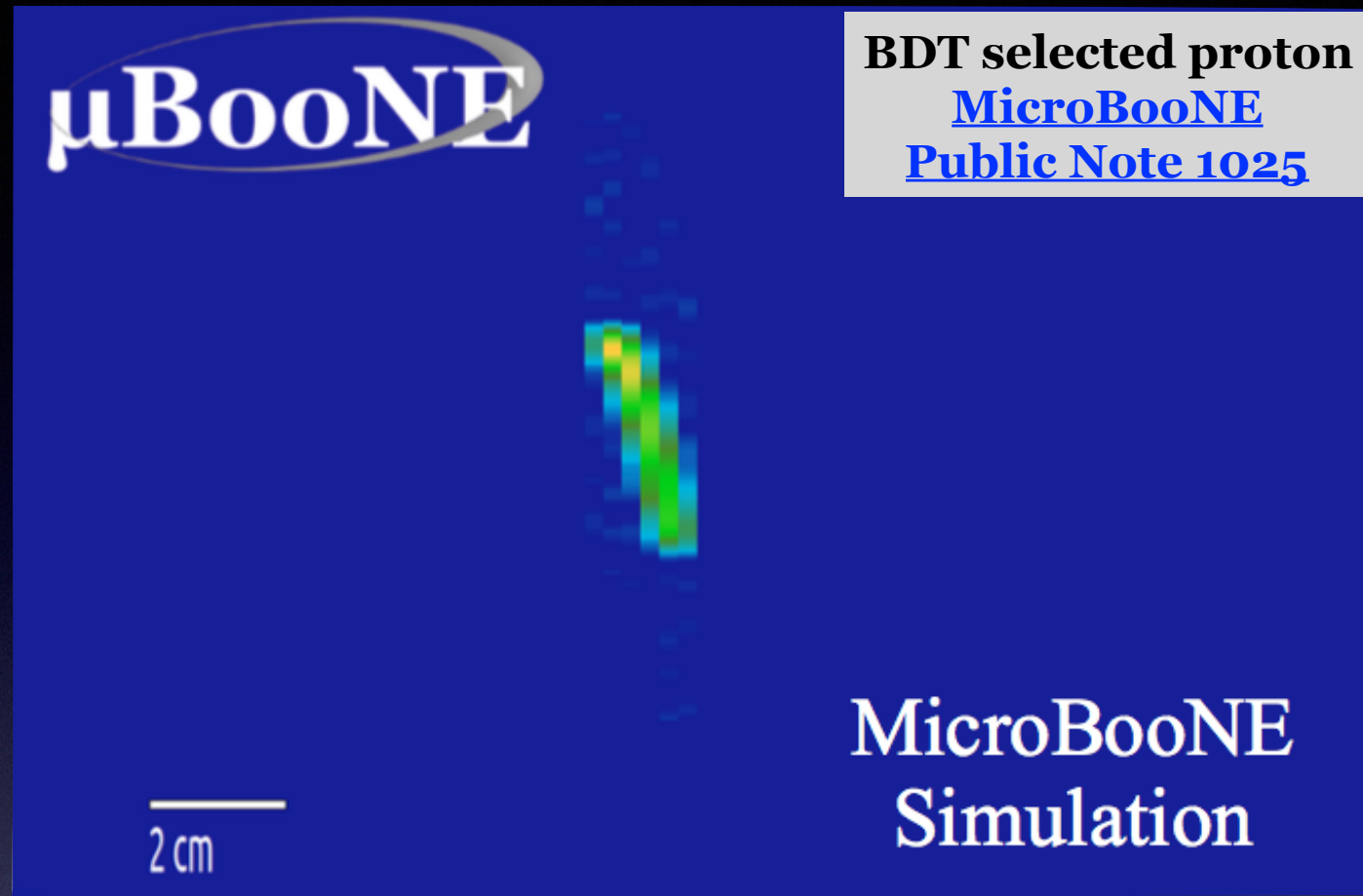
Reconstructed 3D View



Challenges

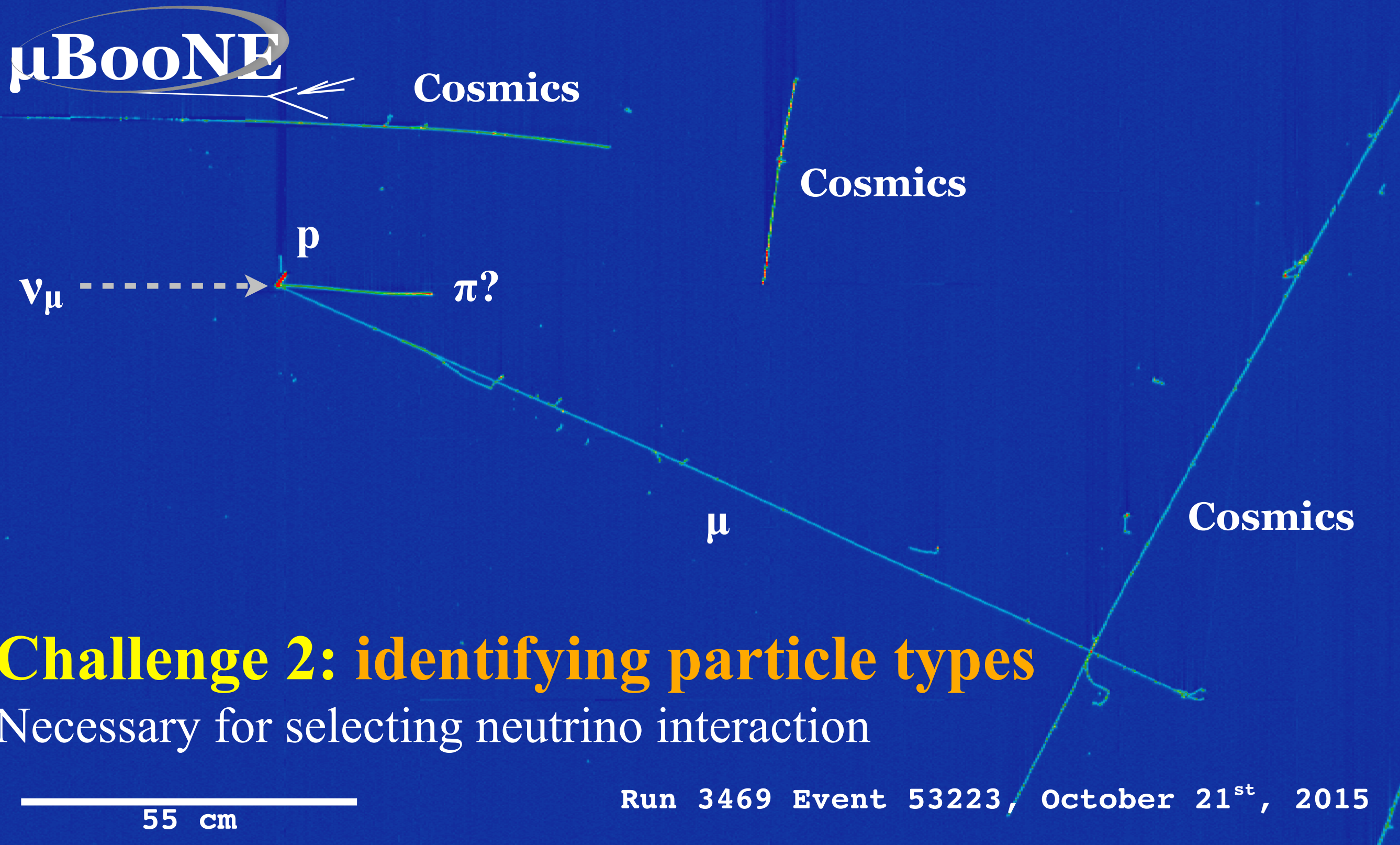
- Complicated event reconstruction
- Small signal, large detector, high rate of un-tagged cosmics

Challenges for Neutrino Analysis (I)



**Challenge 1: small signal,
a large detector filled with cosmes!**

Challenges for Neutrino Analysis (II)



Challenges for Neutrino Analysis (III)

μ BooNE

Challenge 3: Shower Energy

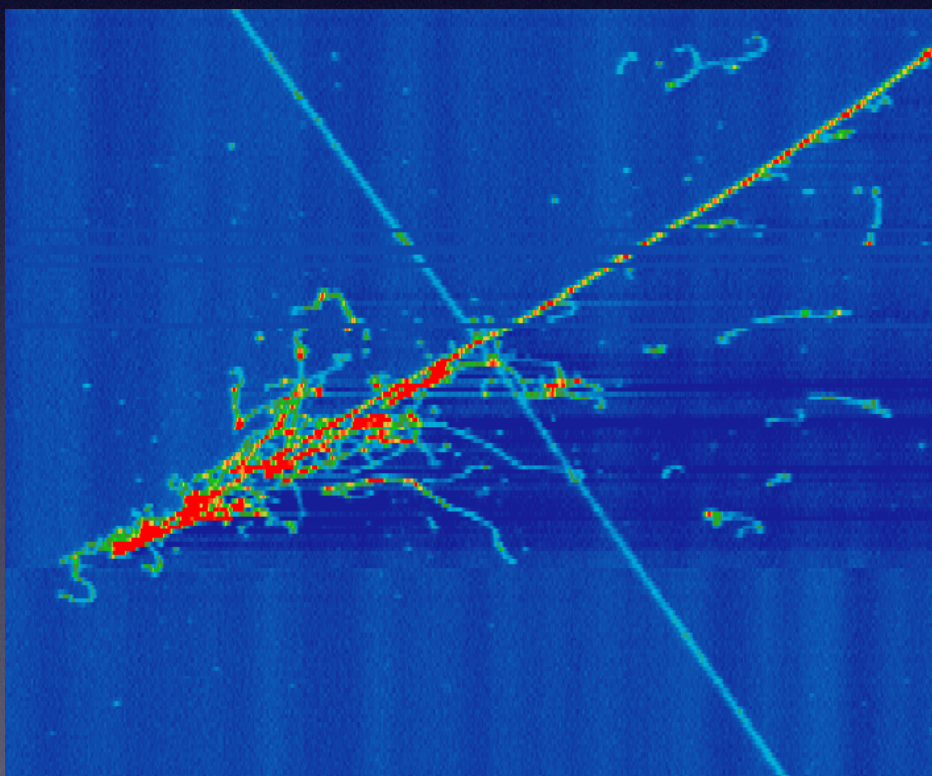
Reconstruction is already hard, and one must cluster all scattered charge depositions to reconstruct energy well



Challenges for Neutrino Analysis (IV)

Challenge 4: programming is not easy

Need efficient, fast pattern recognition algorithms and a framework to run a chain (or multiple chains) of them



Our data is an “image”,
a matrix of numbers

we wish



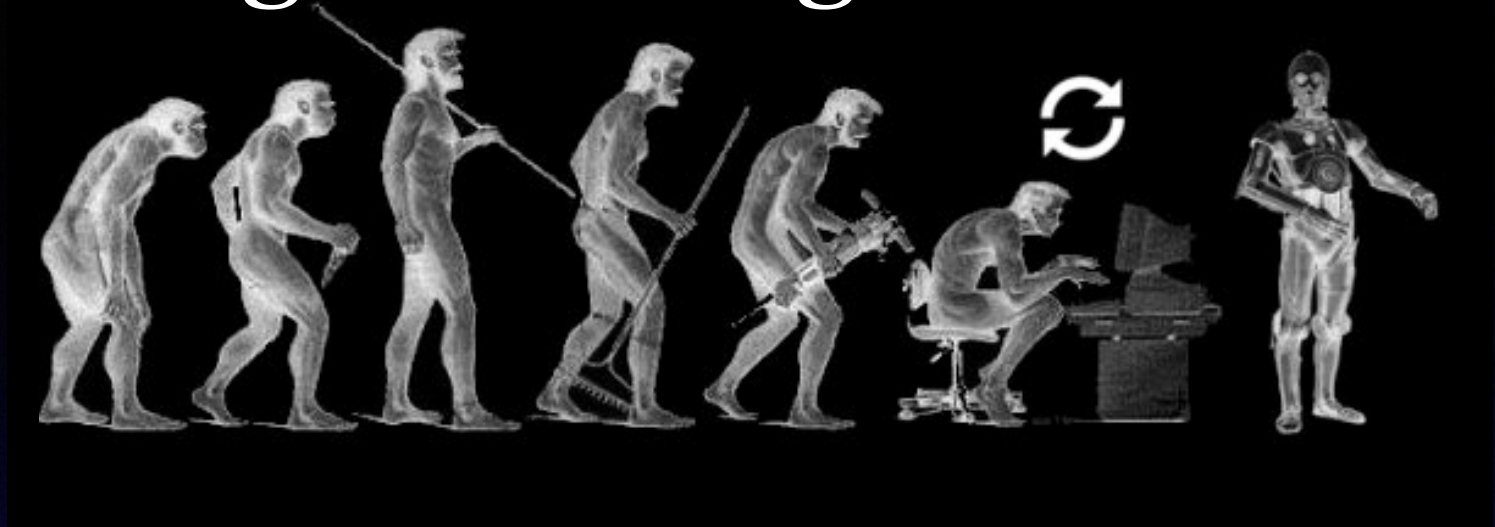
Not how it looks in C++

in reality

```
01101010100101011010101001011010  
10111010101001010100010010101101  
0101001011010101001010110101010  
01011010101001010110101010101101  
0101001010110101010010110101010  
01011010101001010110101010010110  
10101001010110101010101101010100  
10101101010100110101101010100101
```

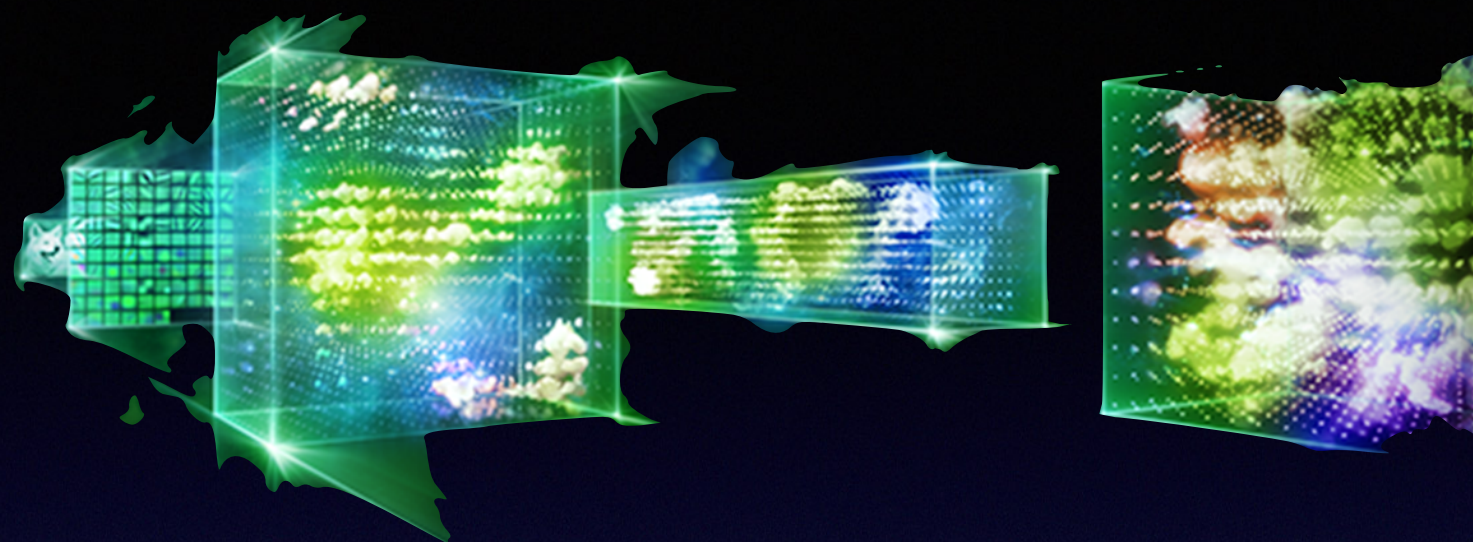
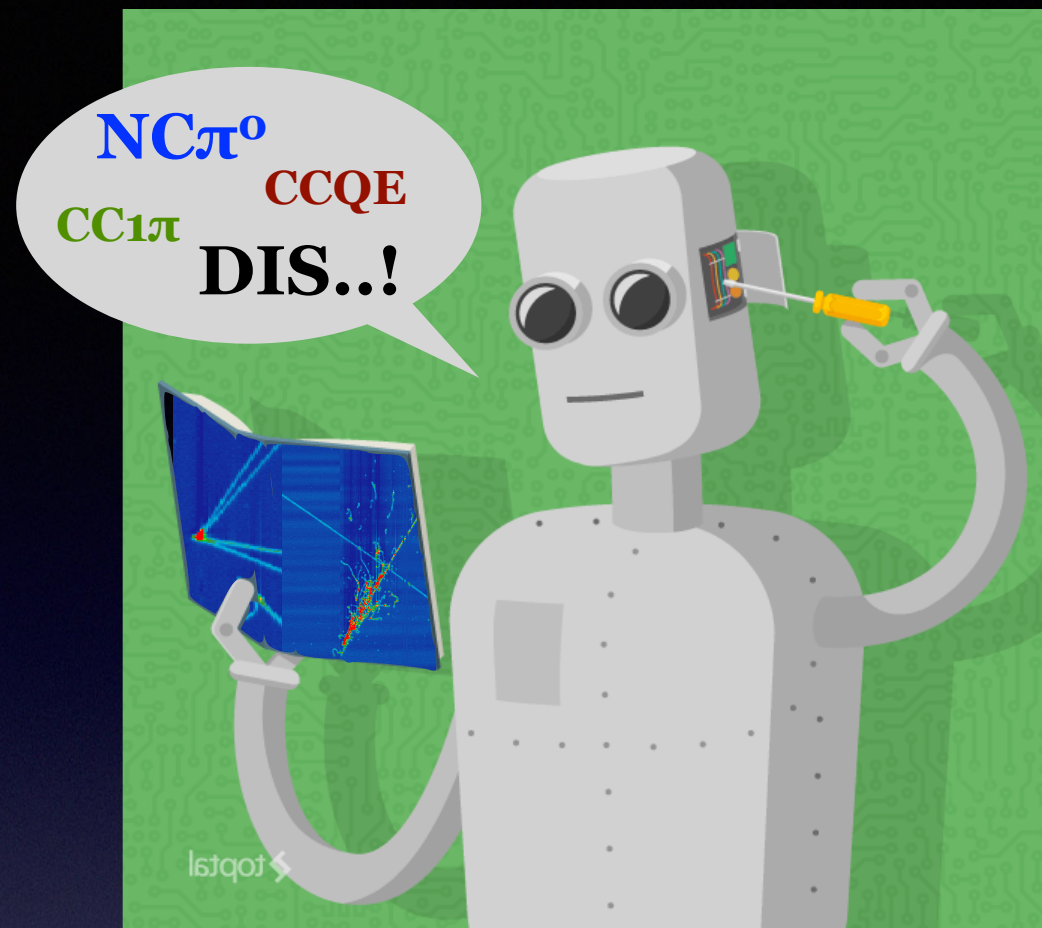
This is how it looks in C++

... enough challenges ...



Solutions?

- **Path A: “traditional path”**
 - Hand-engineered reconstruction algorithms
- **Path B: machine learning**
 - Suited tool for a pattern recognition
 - “**Deep Learning**”
 - ▶ In particular...
 - Convolutional Neural Networks (CNNs)**
 - ▶ Scalable technique, generalizable to various tasks
 - ▶ Superb performance on image data analysis



Convolutional Neural Networks for

LArTPC Analysis

Outline

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CNNs for Image Analysis

Context Analysis

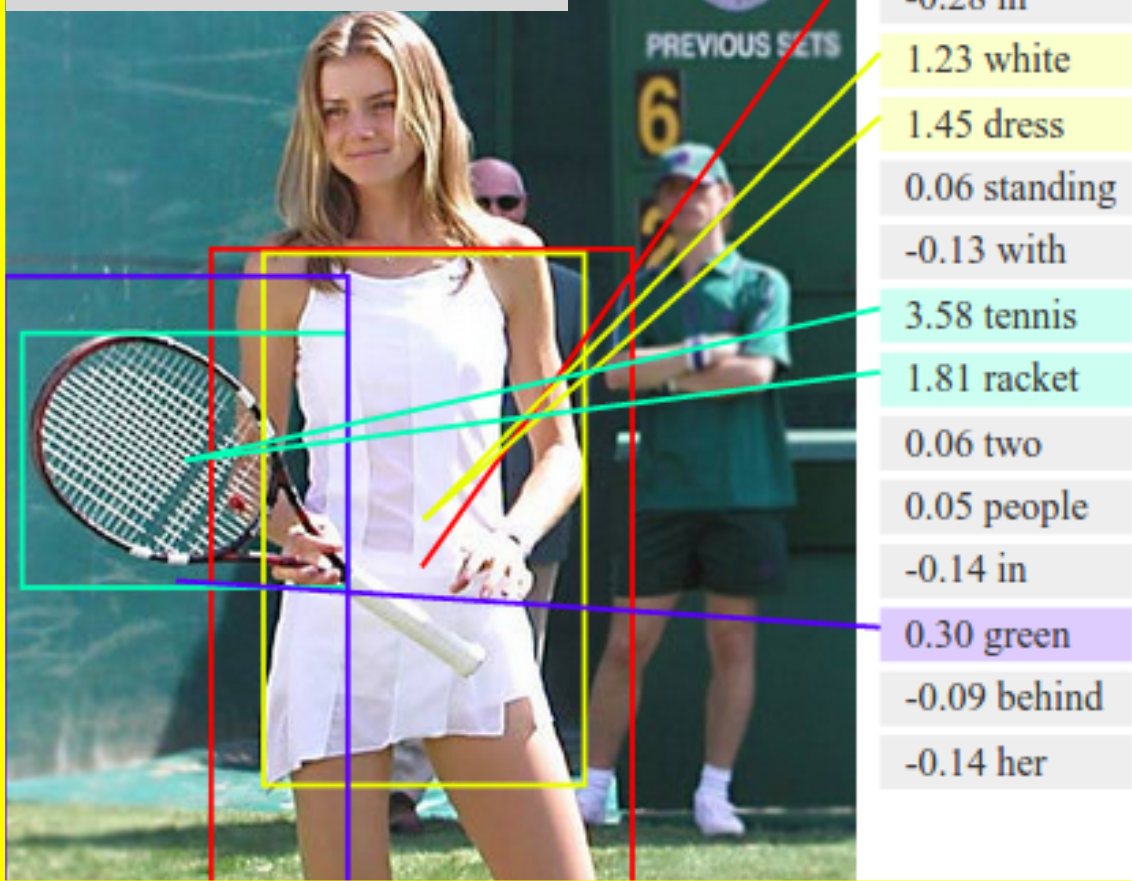
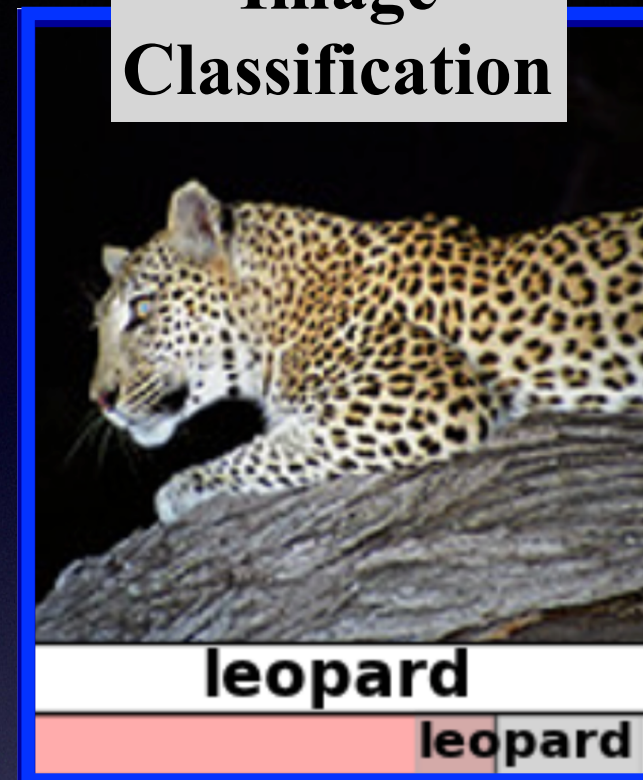
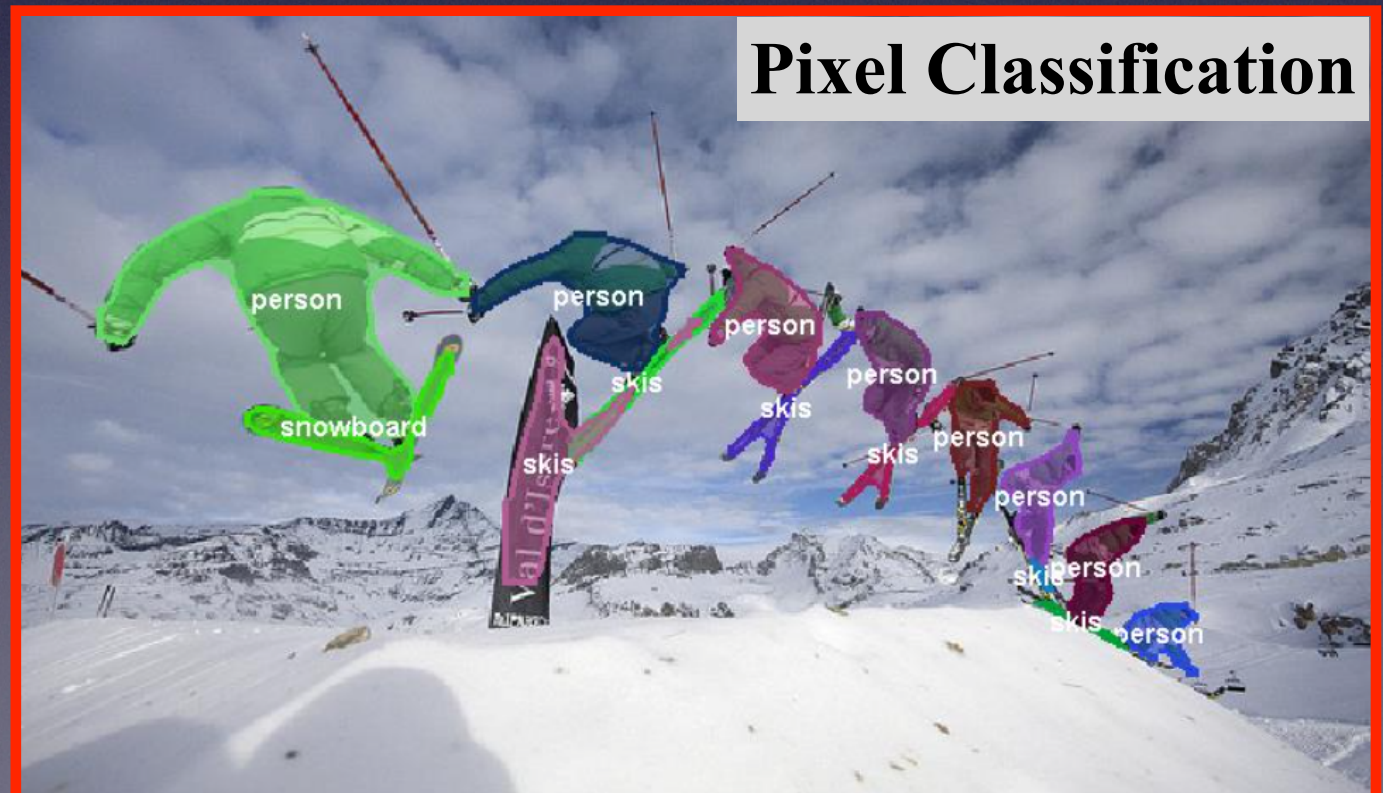


Image Classification



- Superb image analysis capabilities
- Trainable from raw data (large tensor)

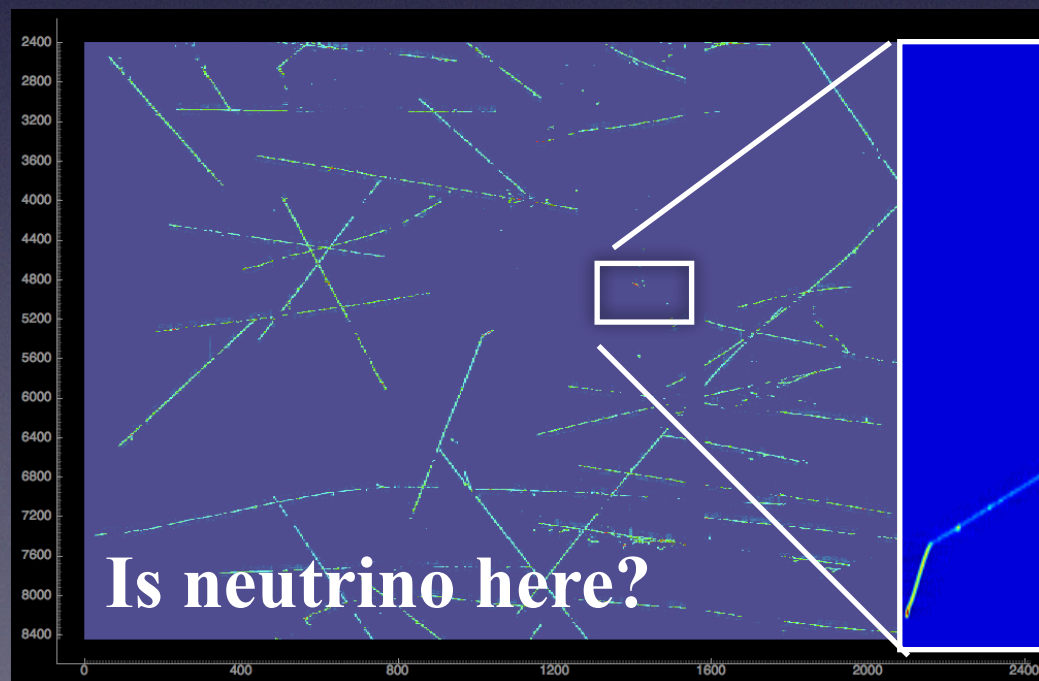
Pixel Classification



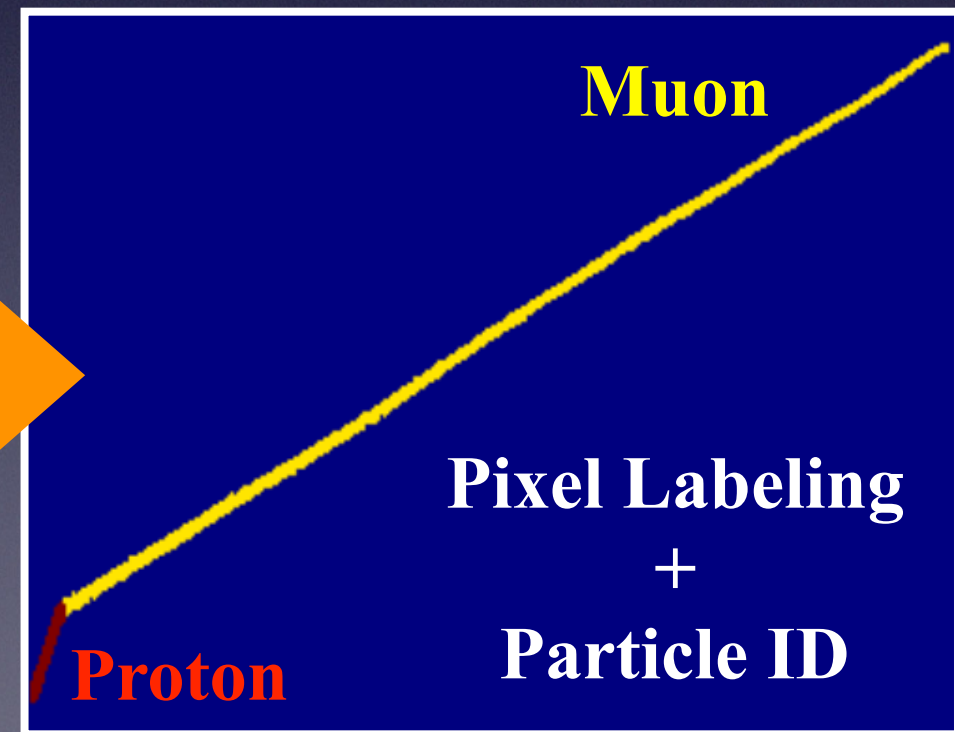
CNN in MicroBooNE (I)

Applications in MicroBooNE

- **Event selection** (image classification)
- **Vertex finding** (object detection)
- **Clustering** (semantic segmentation)
- **Particle identification** (image classification)



Detect interaction
and classify type



$$\nu_{\mu} + n \rightarrow \mu + p$$

CNN in MicroBooNE (I)

Applications in MicroBooNE

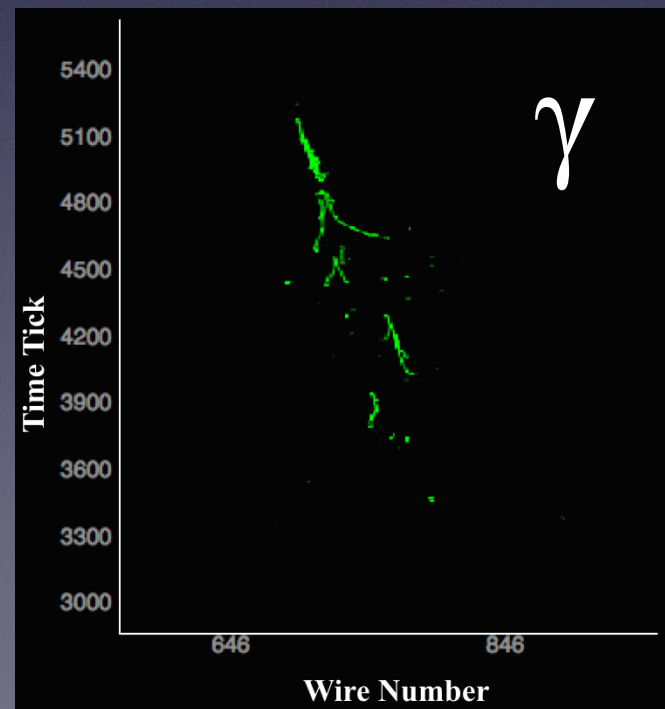
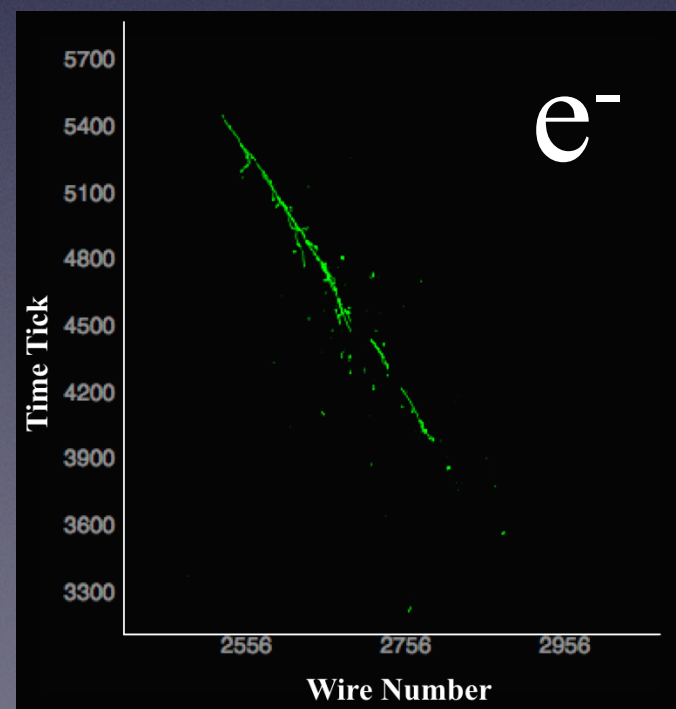
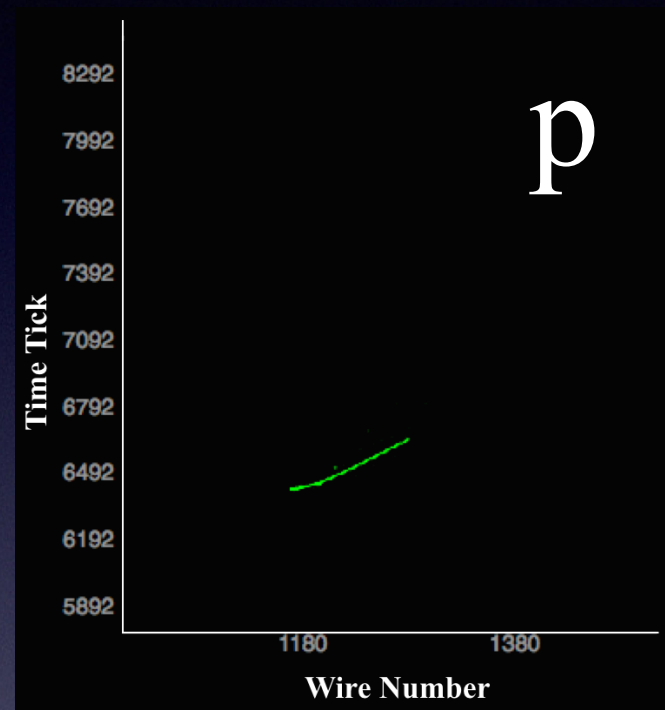
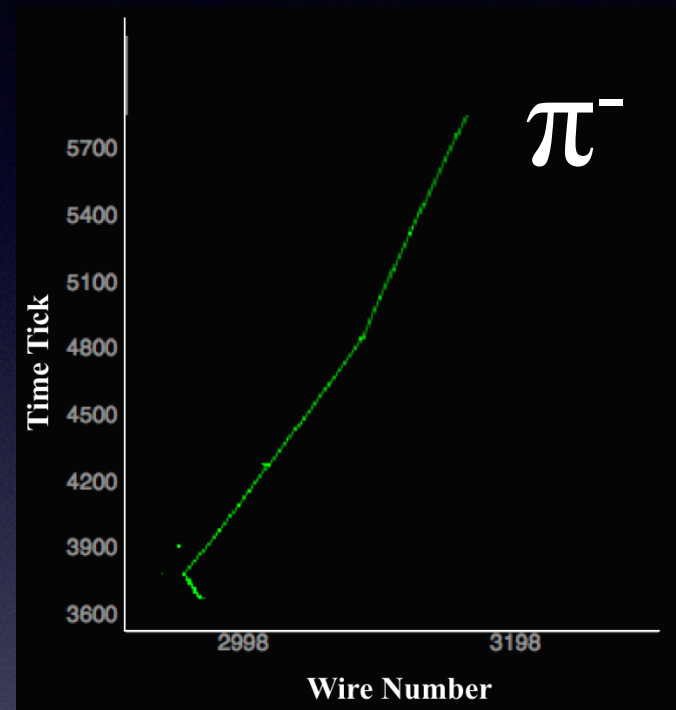
- **Event selection** (image classification)
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- **Clustering** (semantic segmentation)
- **Particle identification** (image classification)

Highlights these CNNs in next slides

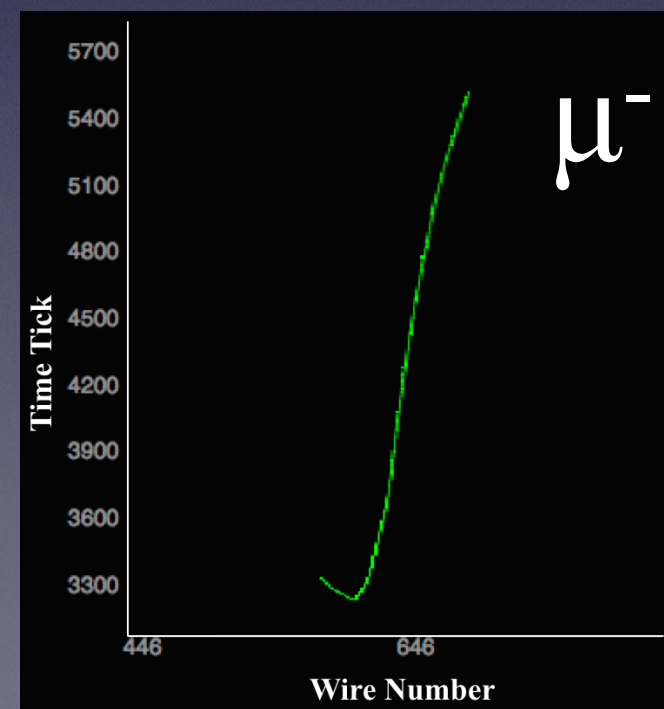
CNN in MicroBooNE (I)

Particle identification

Trained a network to distinguish 5 particle types



- **Simulated particles**
 - using 1 (collection) plane
- **Supervised training**
 - 22,000 images / type
- **Flat momentum dist.**
 - Uniform position
 - Isotropic [100, 1000] MeV/c



CNN in MicroBooNE (I)

Particle identification

Trained a network to distinguish 5 particle types

Particle	Efficiency	Mid-ID
e^-	0.778	γ ... 0.20
γ	0.834	e^- ... 0.15
μ^-	0.897	π^- ... 0.054
π^-	0.710	μ^- ... 0.226
proton	0.912	μ^- ... 0.046

Further improvement?

- ~5 to 10% improvement by exploring network architectures - network width, effective depth
- Additional ~5% improvement by combining 3 planes using siamese architecture

[JINST 10.1088/1748-9221](https://arxiv.org/abs/10.1088/1748-9221)

Resource Usage

Architecture study include performance vs. speed!

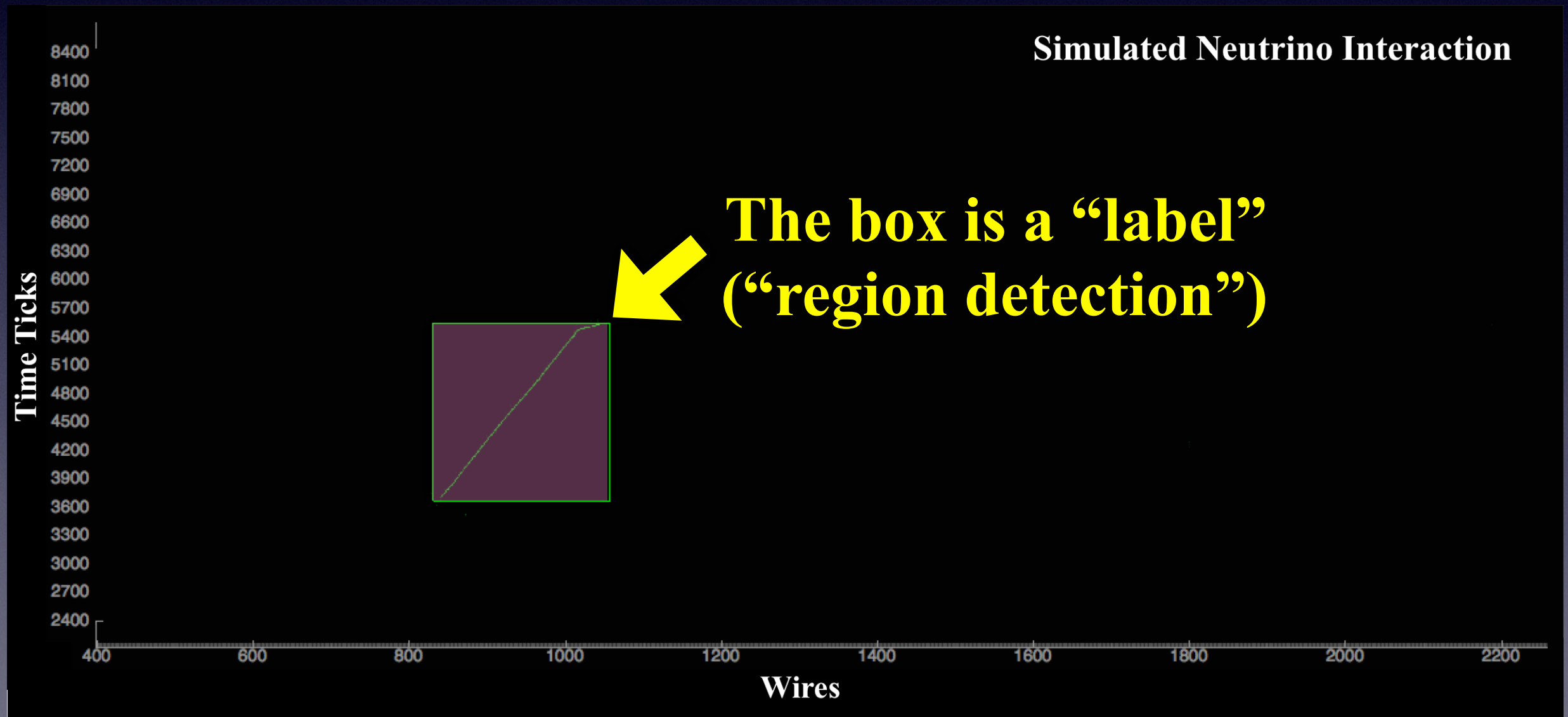
Current architecture choice ~7 ms/image (@ Titan X GPU)

CNN in MicroBooNE (II)

Event vertex detection

Trained a network to find neutrino interaction region

- Training sample uses simulated neutrino + cosmic data image
 - Supervised training using $\approx 100,000$ collection plane images (1-plane)

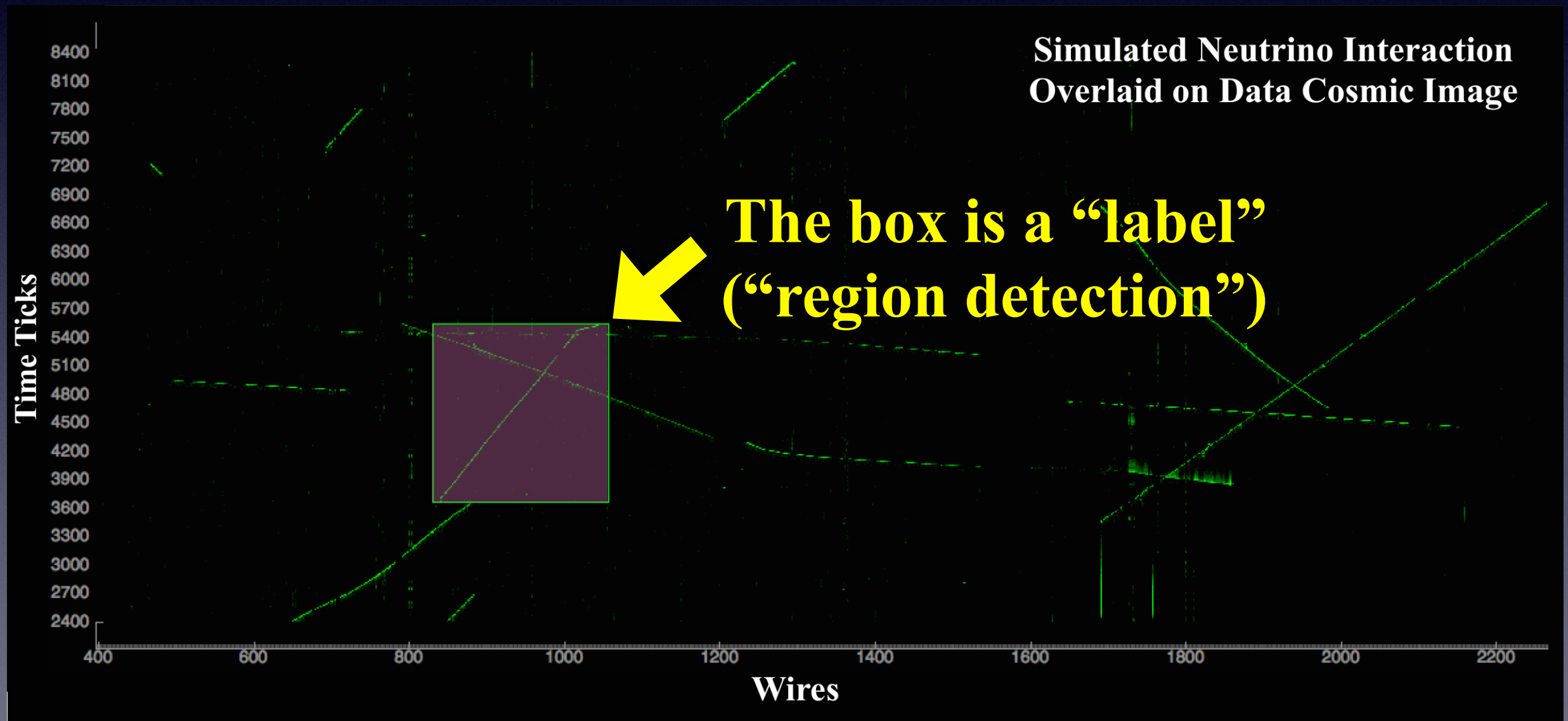


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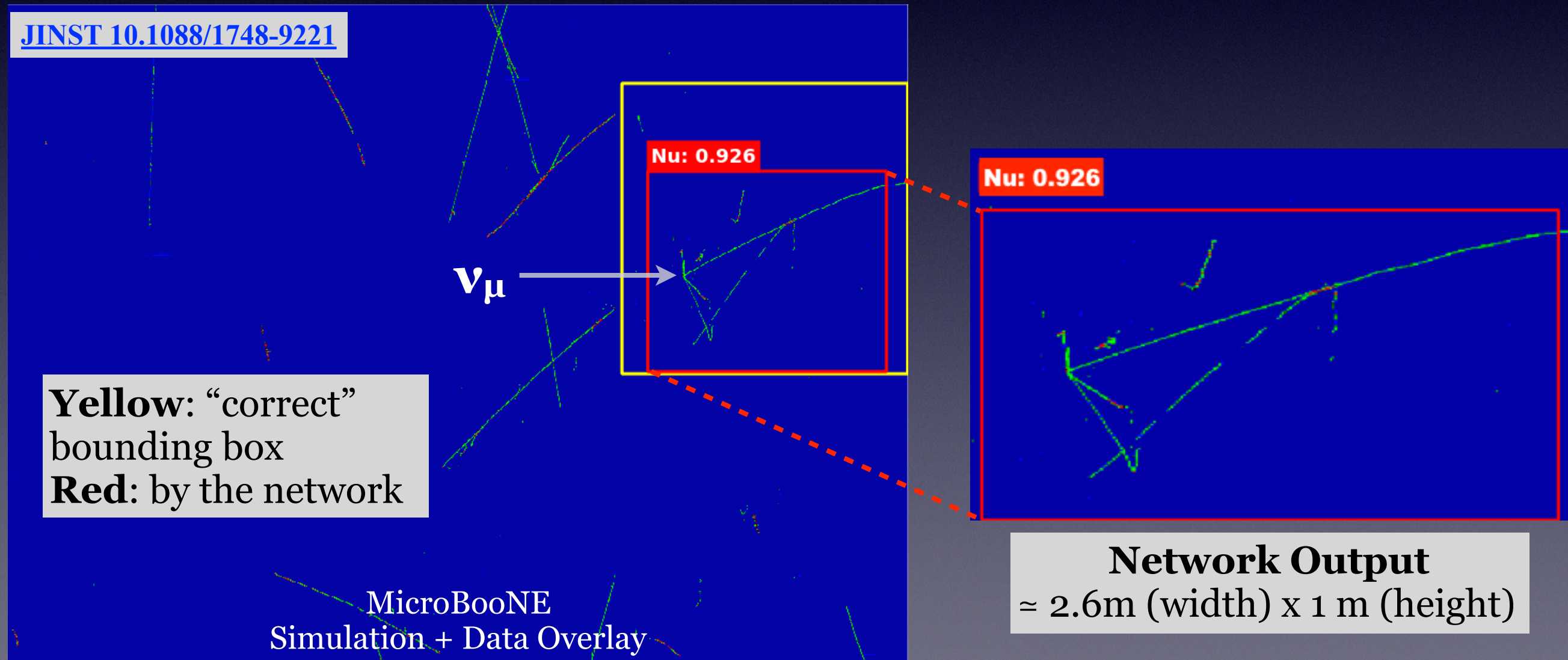


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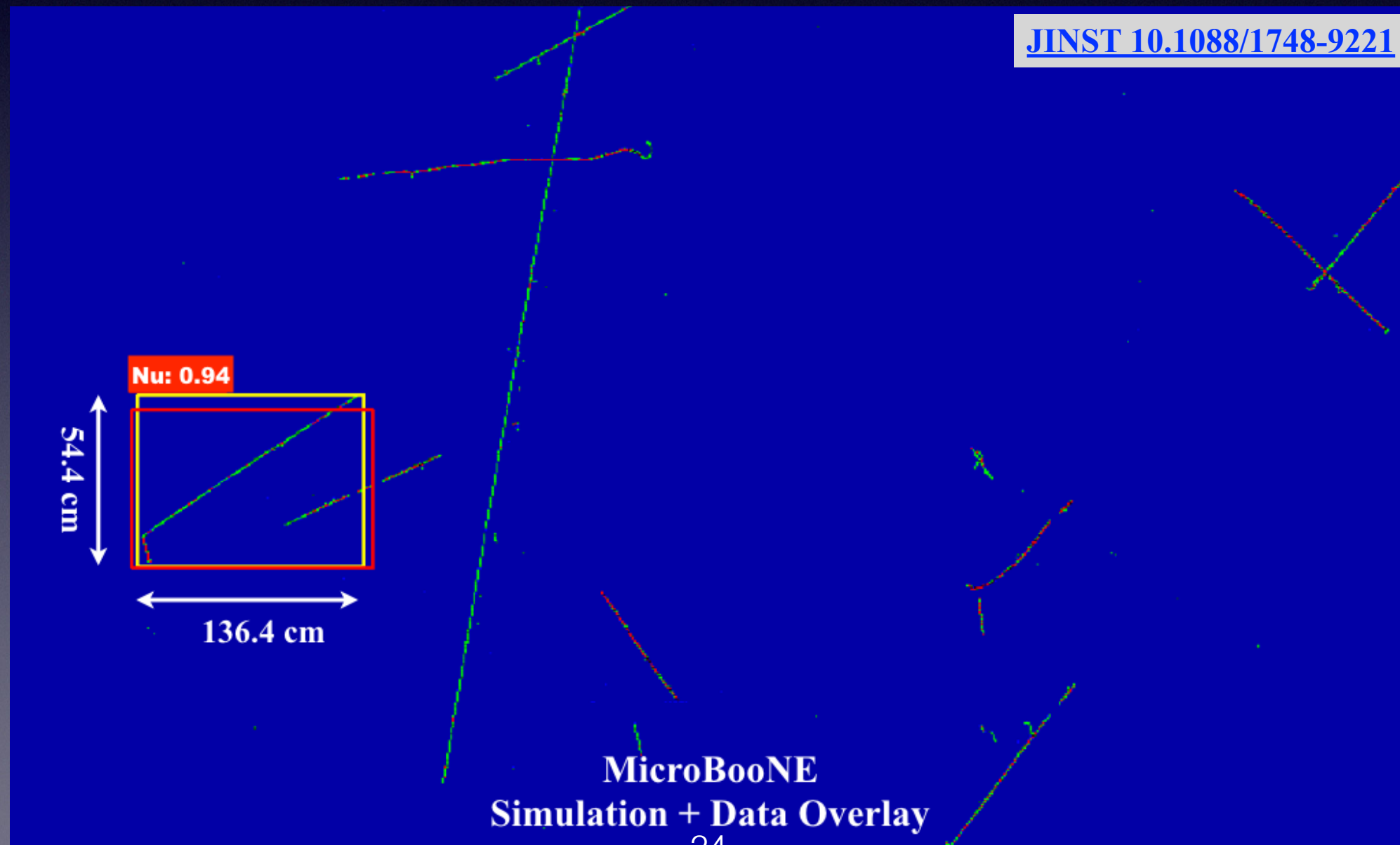


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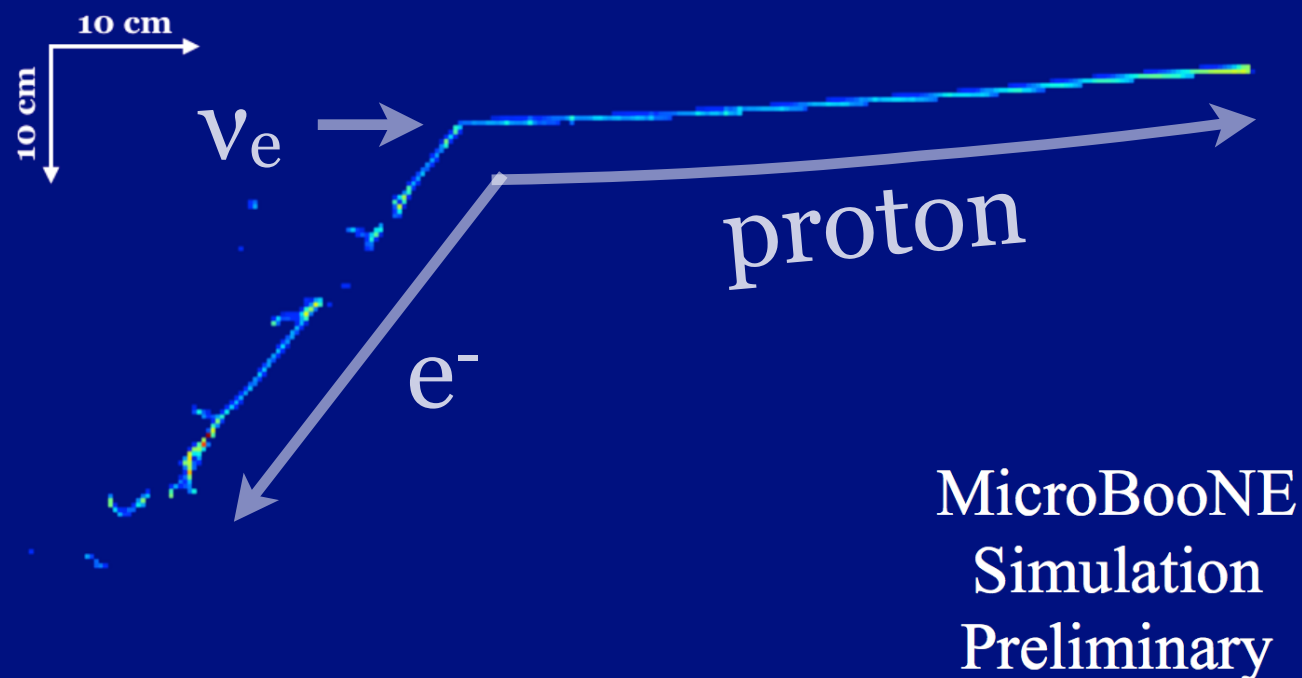


CNN in MicroBooNE (III)

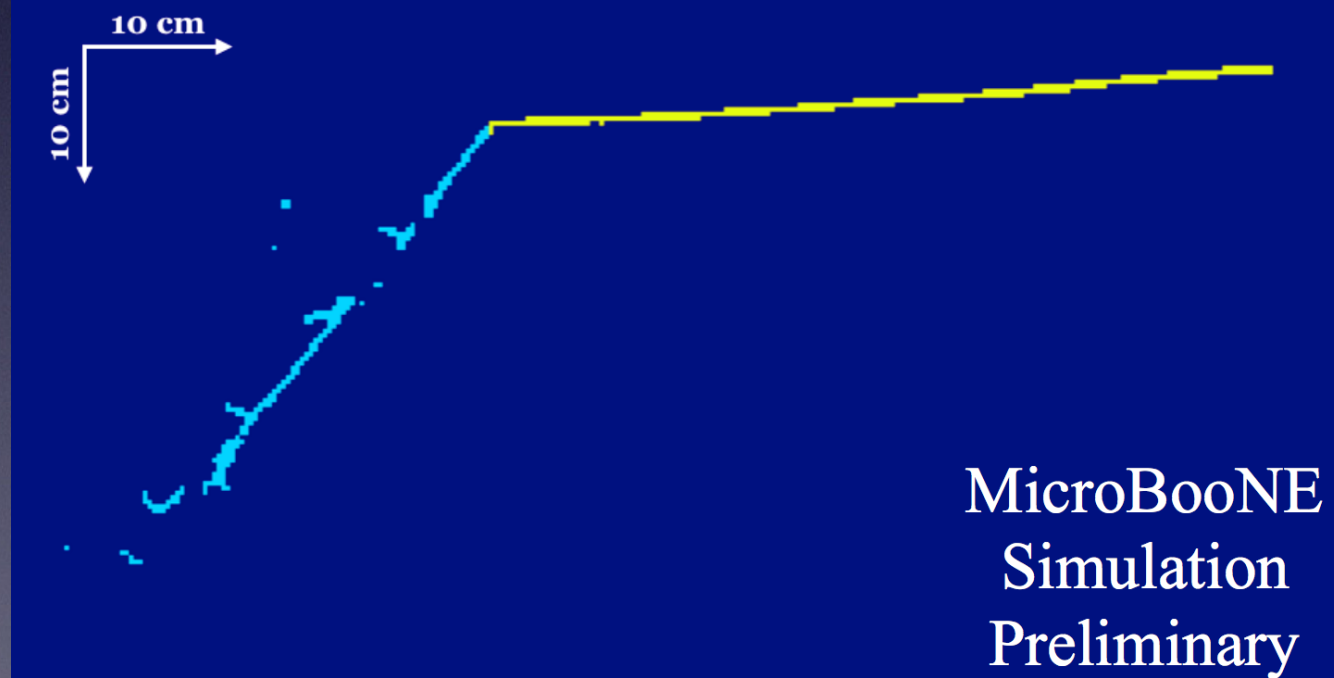
Particle clustering using a network

CNN designed to **segment pixels by predefined semantics**

- Can perform particle-wise pixel clustering
- On-going work
 - “track/shower” pixel labeling by the network (clustered by algorithm)
 - Custom training technique to improve performance on LArTPC image



ADC Image



Network Output

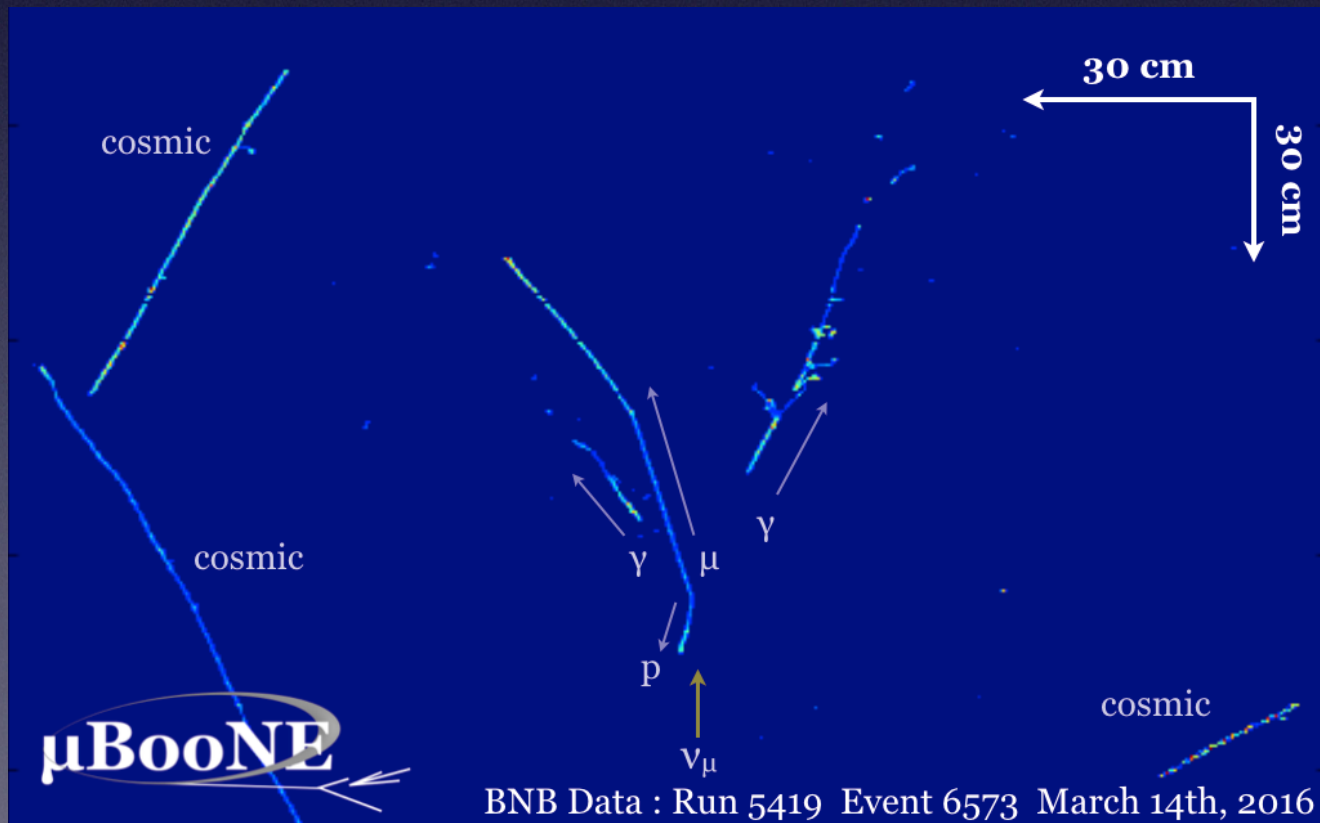
CNN in MicroBooNE (III)

Particle clustering using a network

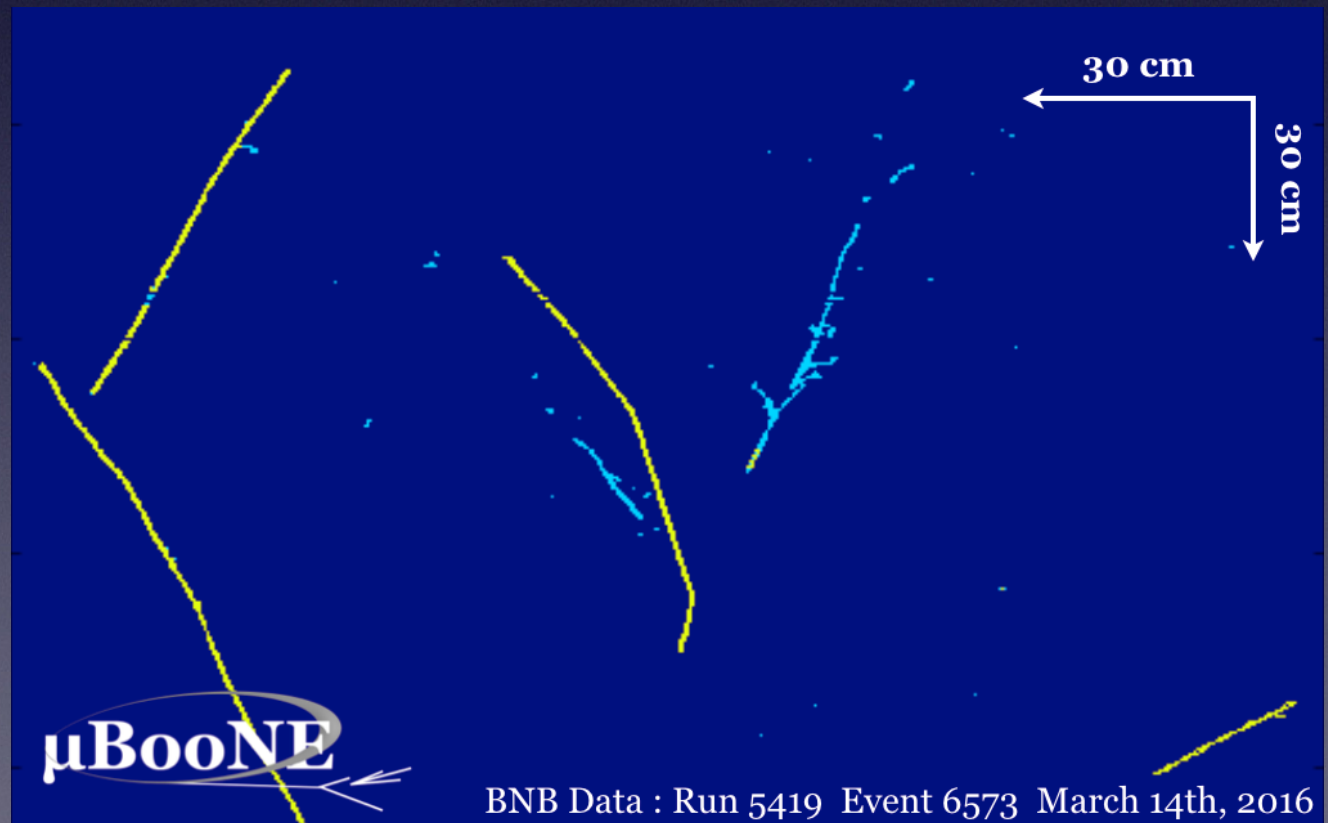
CNN designed to **segment pixel** **semantics**

- Can perform
- On-going work
 - “track/show” labeling by the network (clustered by algorithm)
 - Custom training technique to improve performance on LArTPC image

Also making sure **the networks work on data** as we go!



ADC Image



Network Output

CNN in MicroBooNE (IV)

Optimize multiple tasks together (future project)

“Multi-task Network Cascade” can introduce task dependencies

- Allows to optimize the whole chain together



... sorry for my parenthood ...

CNN in MicroBooNE (V)

Some studies published!

- **Event selection** (image classification)
- **Vertex finding** (object detection)
- **Clustering** (semantic segmentation)
- **Particle identification** (image classification)

Feel free
to contact us
for details!

Cornell University Library

arXiv.org > physics > arXiv:1611.05531

Physics > Instrumentation and Detectors

Convolutional Neural Networks Applied to Neutrino Events in a Liquid Argon Time Projection Chamber

MicroBooNE collaboration: R. Acciarri, C. Adams, R. An, J. Asaadi, M. Auger, L. Bagby, B. Baller, G. Barr, M. Bass, F. Bay, M. Bishai, A. Blake, T. Bolton, L. Bugel, L. Camilleri, D. Caratelli, B. Carls, R. Castillo Fernandez, F. Cavanna, H. Chen, E. Church, D. Cianci, G. H. Collin, J. M. Conrad, M. Convery, J. I. Crespo-Anadón, M. Del Tutto, D. Devitt, S. Dytman, B. Eberly, A. Ereditato, L. Escudero Sanchez, J. Esquivel, B. T. Fleming, W. Foreman, A. P. Furmanski, G. T. Garvey, V. Genty, D. Goeldi, S. Gollapinni, N. Graf, E. Gramellini, H. Greenlee, R. Grosso, R. Guenette, A. Hackenburg, P. Hamilton, O. Hen, J. Hewes, C. Hill, J. Ho, G. Horton-Smith, C. James, J. Jan de Vries, C.-M. Jen, L. Jiang, R. A. Johnson, B. J. P. Jones, J. Joshi, H. Jostlein, D. Kaleko, G. Karagiorgi, W. Ketchum, et al. (75 additional authors not shown)

(Submitted on 17 Nov 2016)

We present several studies of convolutional neural networks applied to data coming from the MicroBooNE detector, a liquid argon time projection chamber (LArTPC). The algorithms studied include the classification of single particle images, the localization of single particle and neutrino interactions in an image, and the detection of a simulated neutrino event overlaid with cosmic ray backgrounds taken from real detector data. These studies demonstrate the potential of convolutional neural networks for particle identification or event detection on simulated neutrino interactions. We also address technical issues that arise when applying this technique to data from a large LArTPC at or near ground level.

MicroBooNE's 1st paper
JINST 10.1088/1748-9221
arXiv 1611.05531

CNN in MicroBooNE (VI)

LArTPC “real data” sample

MicroBooNE provides LArTPC image data from the real detector

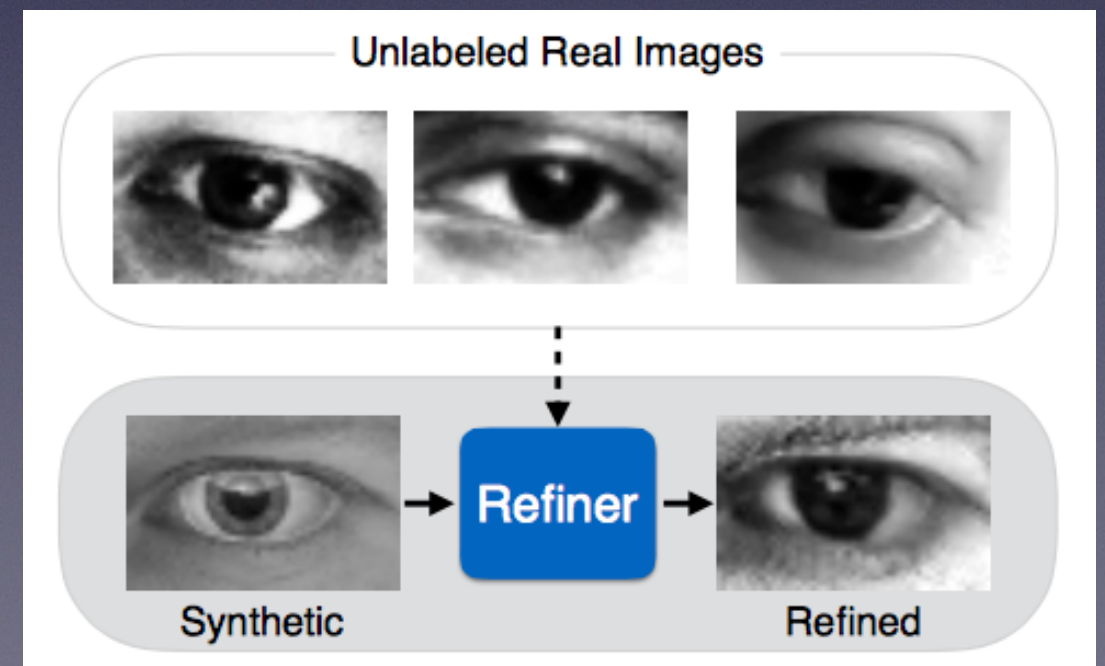
“Labeled” image database

- “neutrino event or not”, “region of interaction”, “particle type”, etc...
- **Key to accelerate the technique R&D** (similar to ILSVRC in CV)

Generative Adversarial Networks (GANs)

- New technique, great intellectual interest in the field (both CV and HEP)
- Possibility to **learn generic image features from real data**
 - Semi-supervised or unsupervised learning
- Example applications
 - LArTPC image generator
 - **MC image “encoder”**
 - Refine “MC images” into “data images”

“**encoder**” for human eye illustration
by Apple research team
[arXiv:1612.07828](https://arxiv.org/abs/1612.07828)



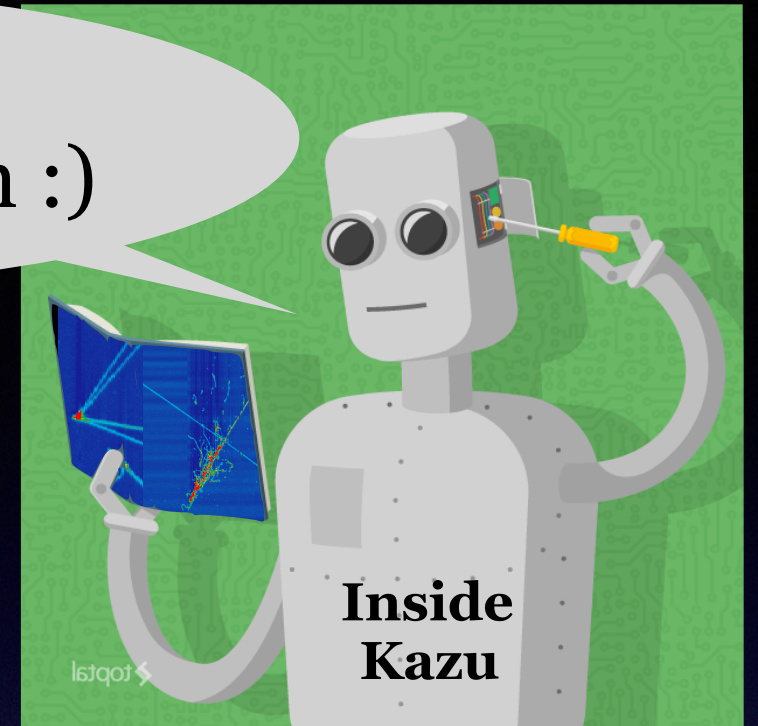


... **wrapping up** ...

Outline

- Machine learning apps in MicroBooNE
- LArTPC image data + challenges
- Convolutional Neural Networks in MicroBooNE
- **Summary**

Thank you!
for your attention :)

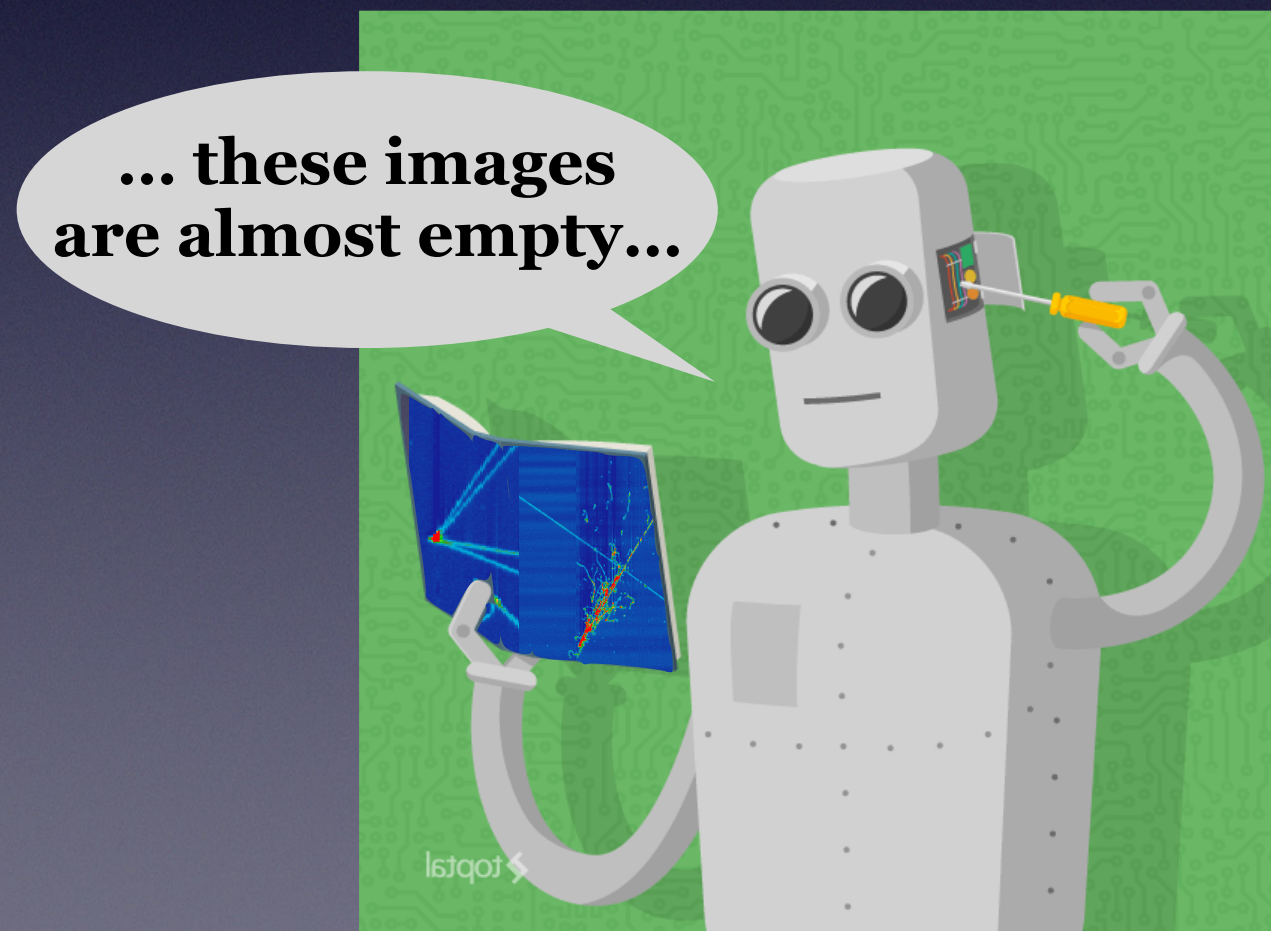


Take Away Messages

1. **LArTPCs** are **high precision detectors**
2. **LArTPCs** need **advanced pattern recognition algorithms**
3. **MicroBooNE** utilize **CNN for reconstruction/analysis**
4. **MicroBooNE** provides **unique opportunity to study real large scale LArTPC image data**, and **important challenges to overcome for future LArTPC detectors**

Back up

CNN for LArTPC Image Analysis

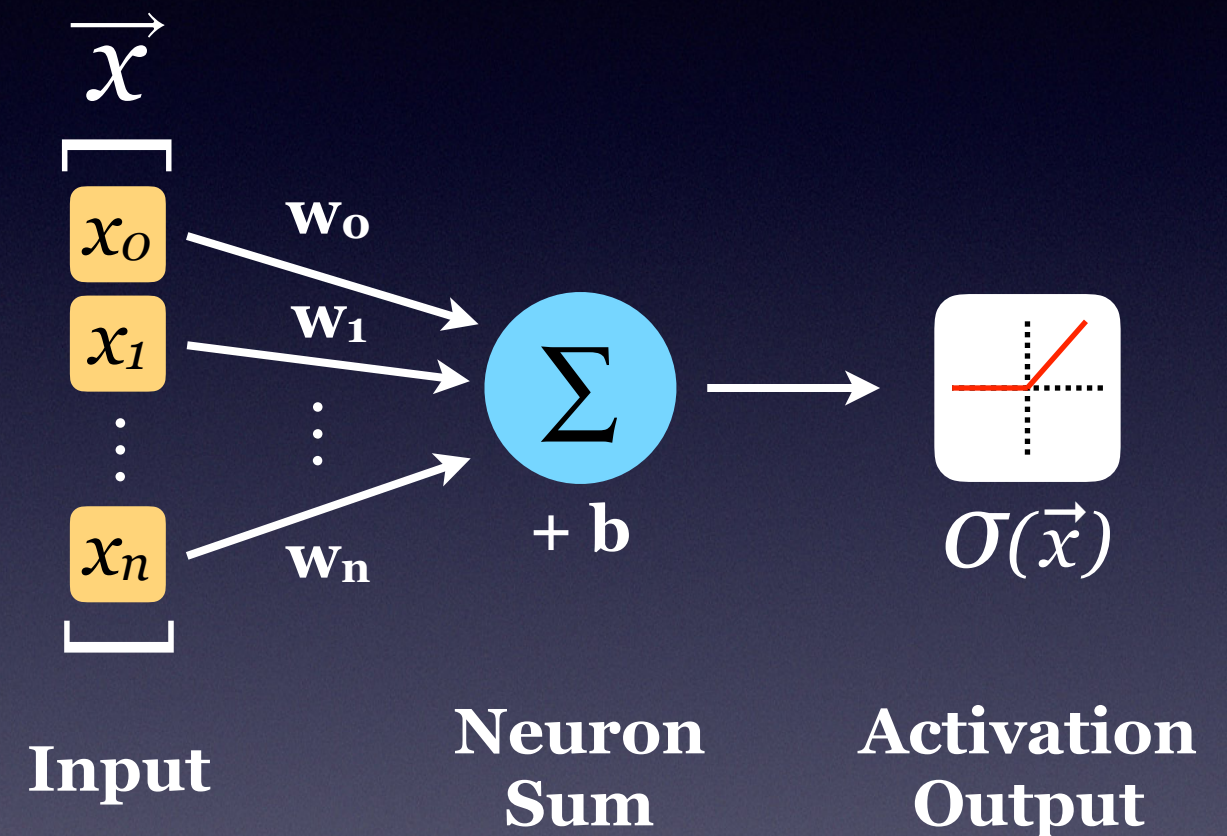


Introduction to CNNs (II)

Background: Neural Net

The basic unit of a neural net is the *perceptron* (loosely based on a real neuron)

Takes in a vector of inputs (x). Commonly inputs are summed with weights (w) and offset (b) then run through activation.

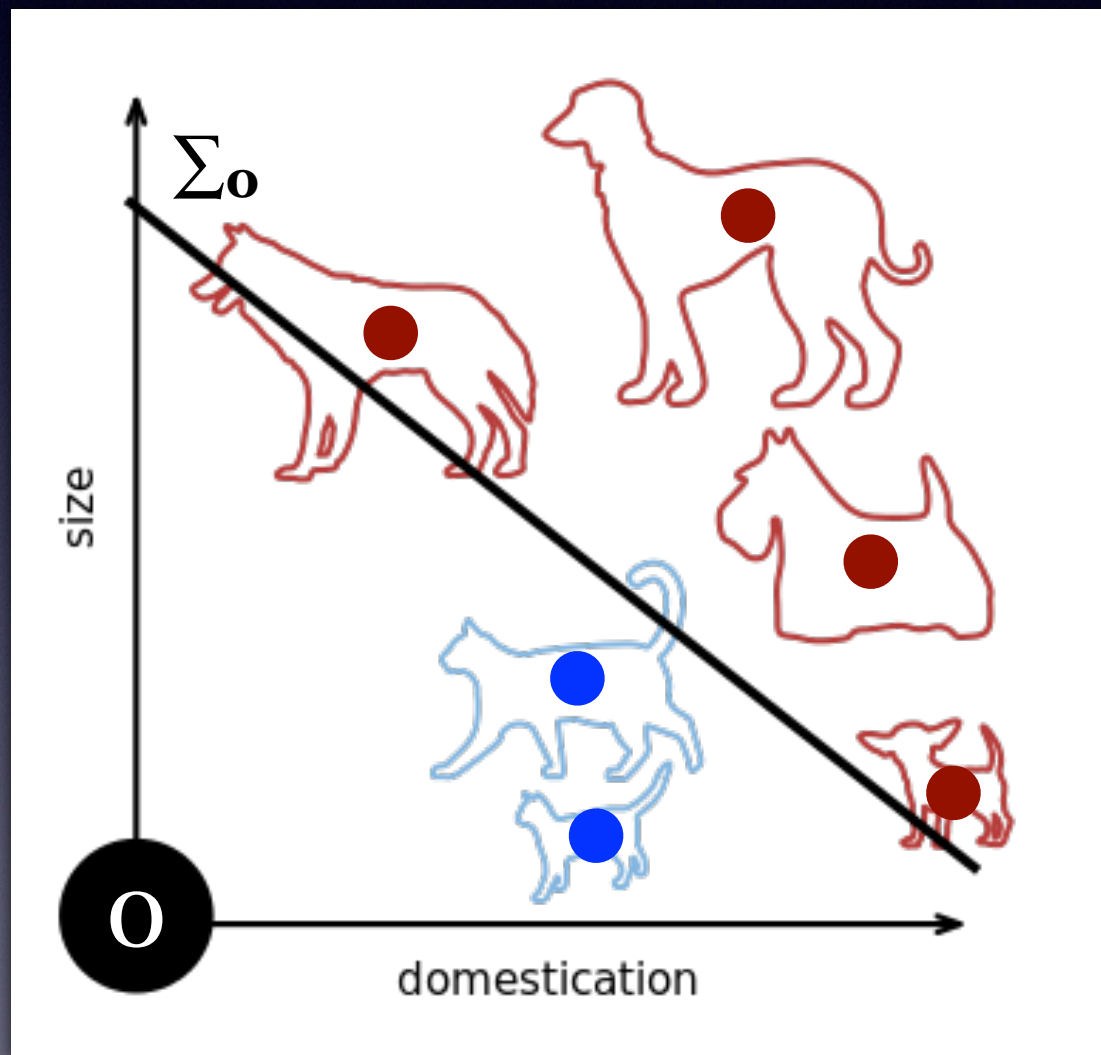


$$\sigma(\vec{x}) = \begin{cases} \vec{w}_i \cdot \vec{x} + b_i & \vec{w}_i \cdot \vec{x} + b_i \geq 0 \\ 0 & \vec{w}_i \cdot \vec{x} + b_i < 0. \end{cases}$$

Introduction to CNNs (II)

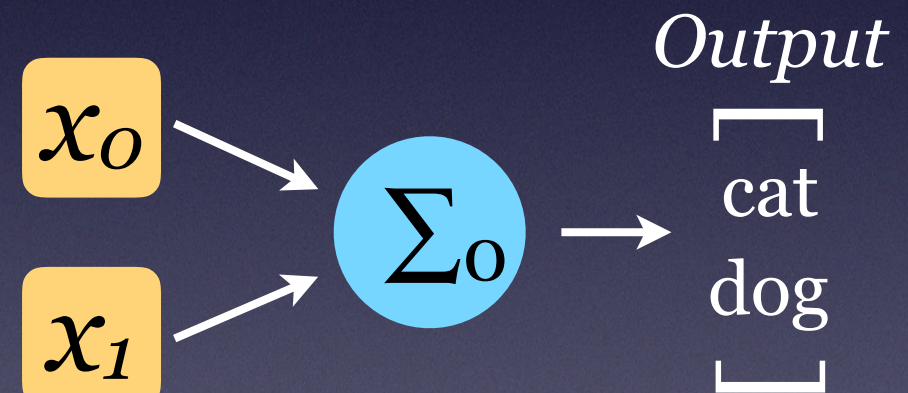
Perceptron 2D Classification

Imagine using two features to separate cats and dogs



from [wikipedia](#)

$$\sigma(\vec{x}) = \begin{cases} \vec{w}_i \cdot \vec{x} + b_i & \vec{w}_i \cdot \vec{x} + b_i \geq 0 \\ 0 & \vec{w}_i \cdot \vec{x} + b_i < 0. \end{cases}$$

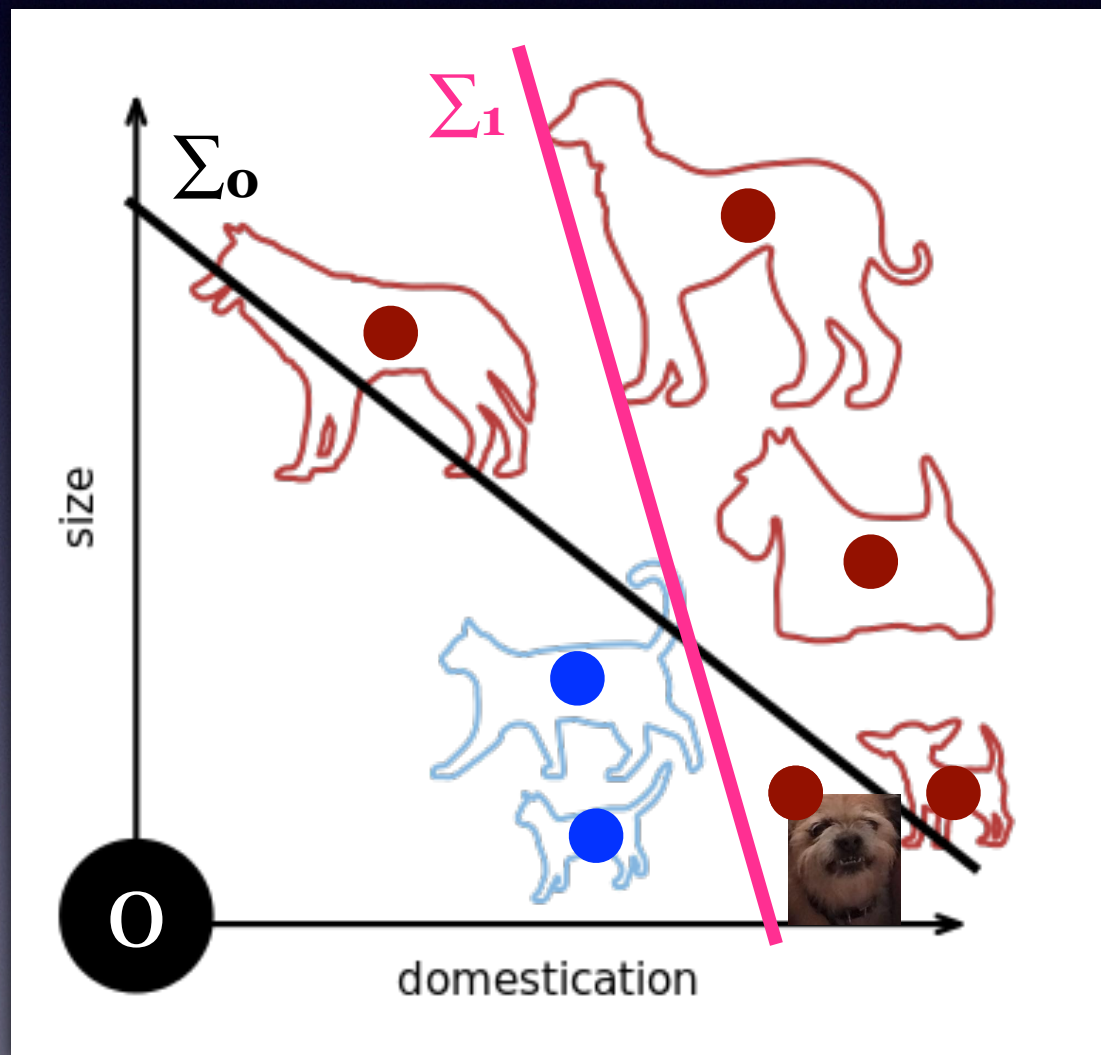


By picking a value for w and b ,
we define a boundary
between the two sets of data

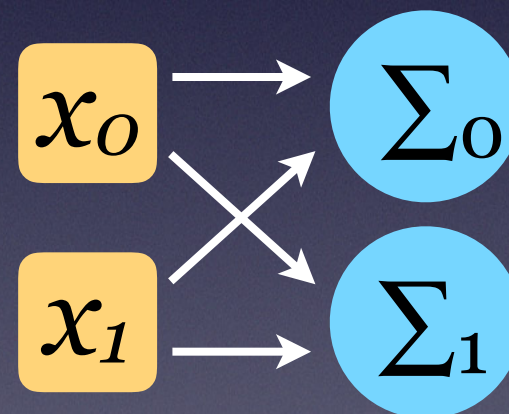
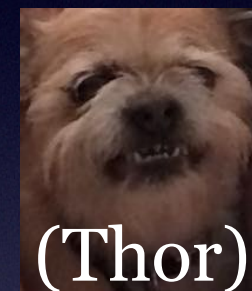
Introduction to CNNs (II)

Perceptron 2D Classification

Maybe we need to do better: assume new data point
(My friend's dog — small but not as well behaved)



from [wikipedia](#)

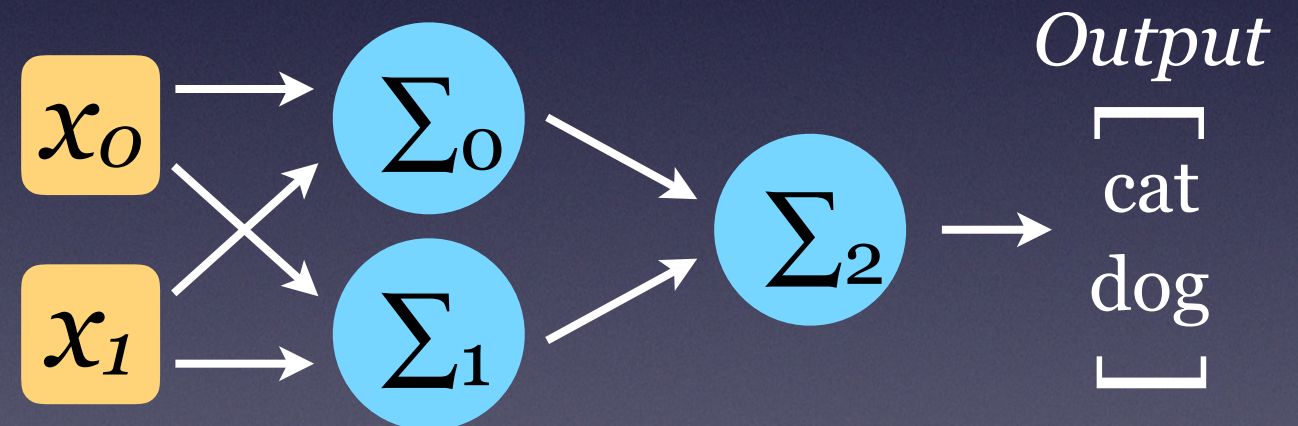
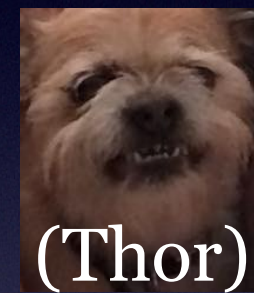
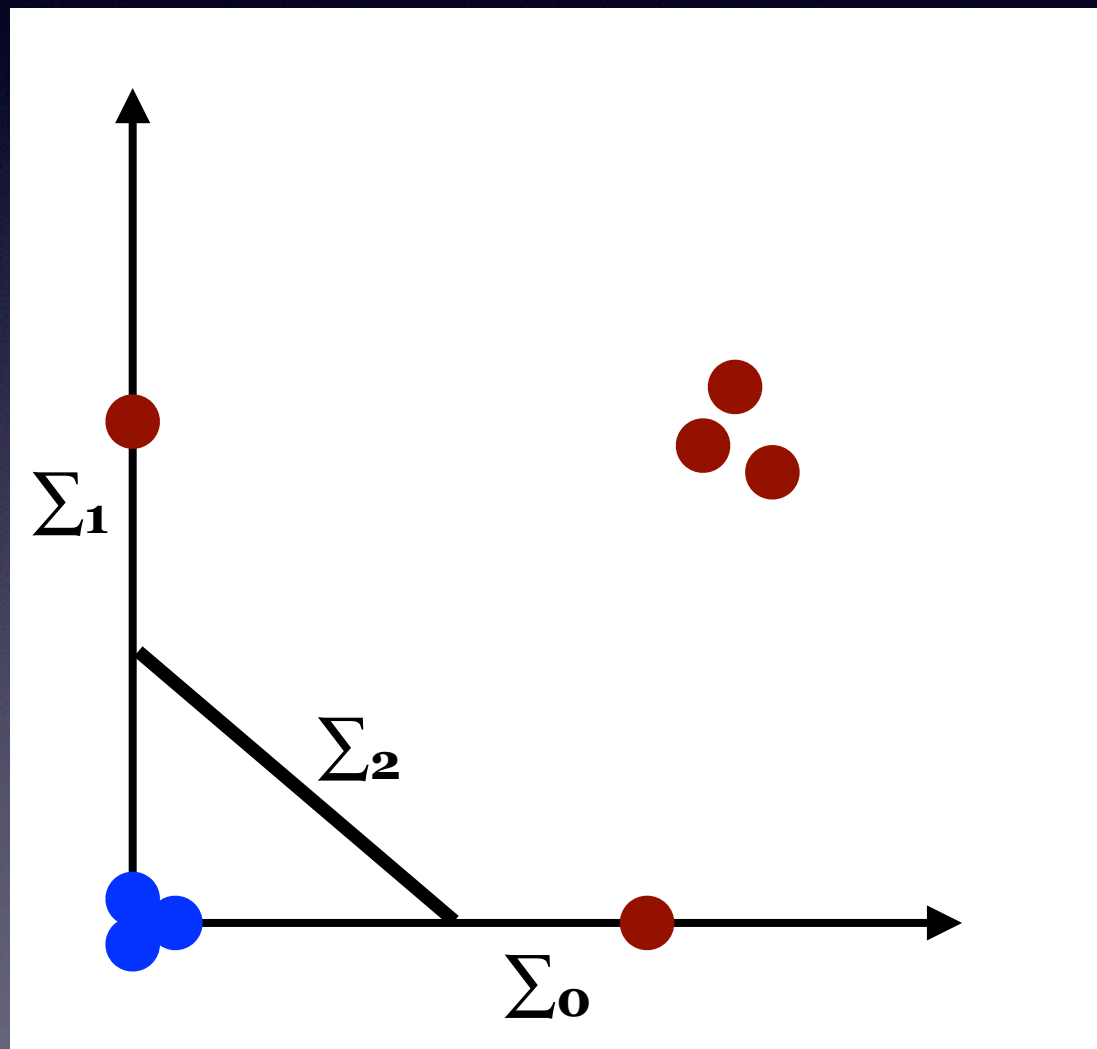


We can add another perceptron
to help classify better

Introduction to CNNs (II)

Perceptron 2D Classification

Maybe we need to do better: assume new data point
(My friend's dog — small but not as well behaved)

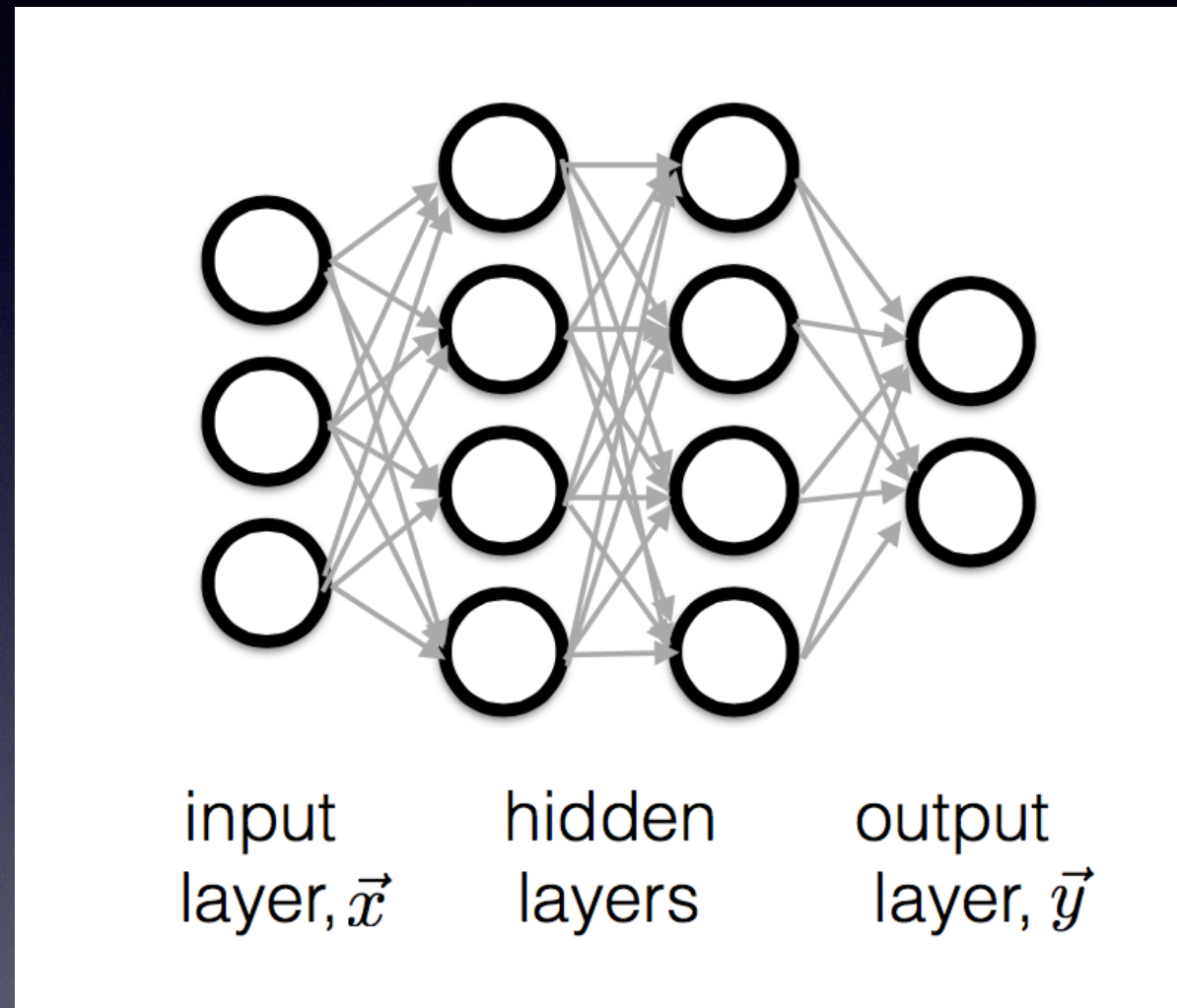


Another layer can classify based on
preceding feature layer output

Introduction to CNNs (III)

“Traditional neural net” in HEP

Fully-Connected Multi-Layer Perceptrons

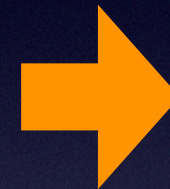
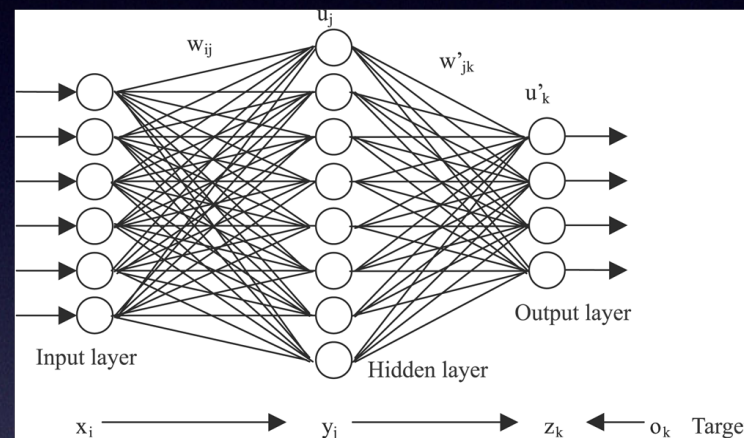
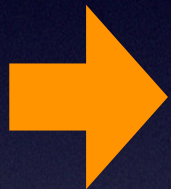
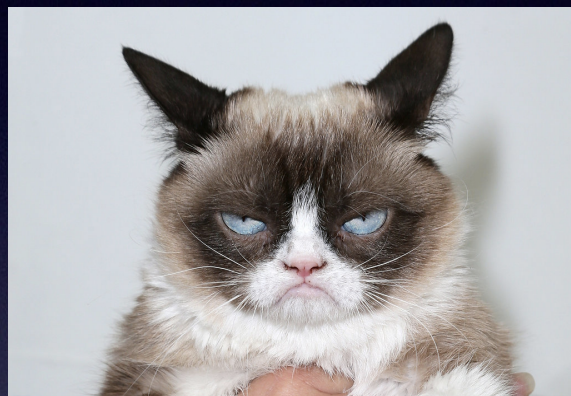


A traditional neural network consists of a stack of layers of such neurons where each neuron is *fully connected* to other neurons of the neighbor layers

Introduction to CNNs (III)

“Traditional neural net” in HEP Problems with it...

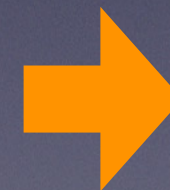
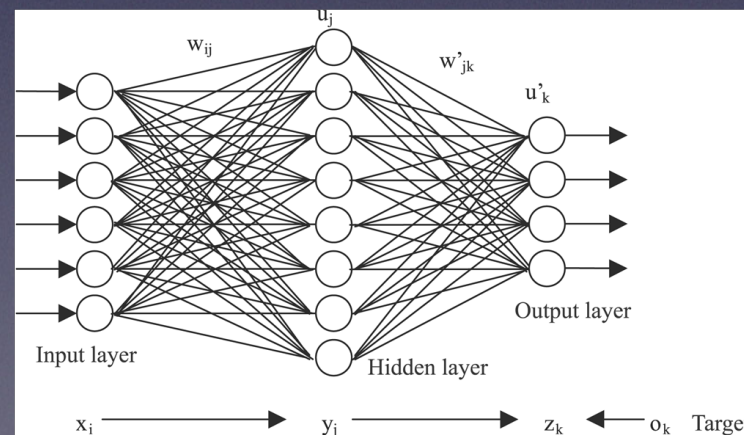
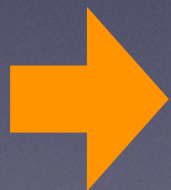
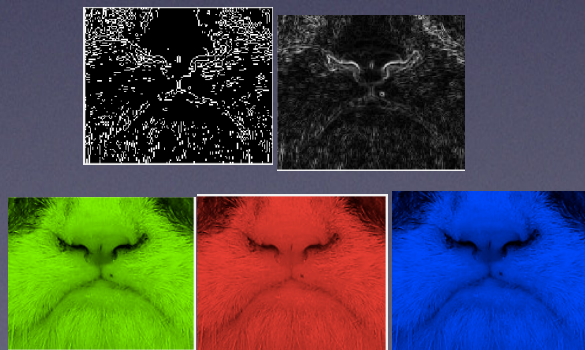
Feed in entire image



Cat?

Problem: scalability

Use pre-determined features

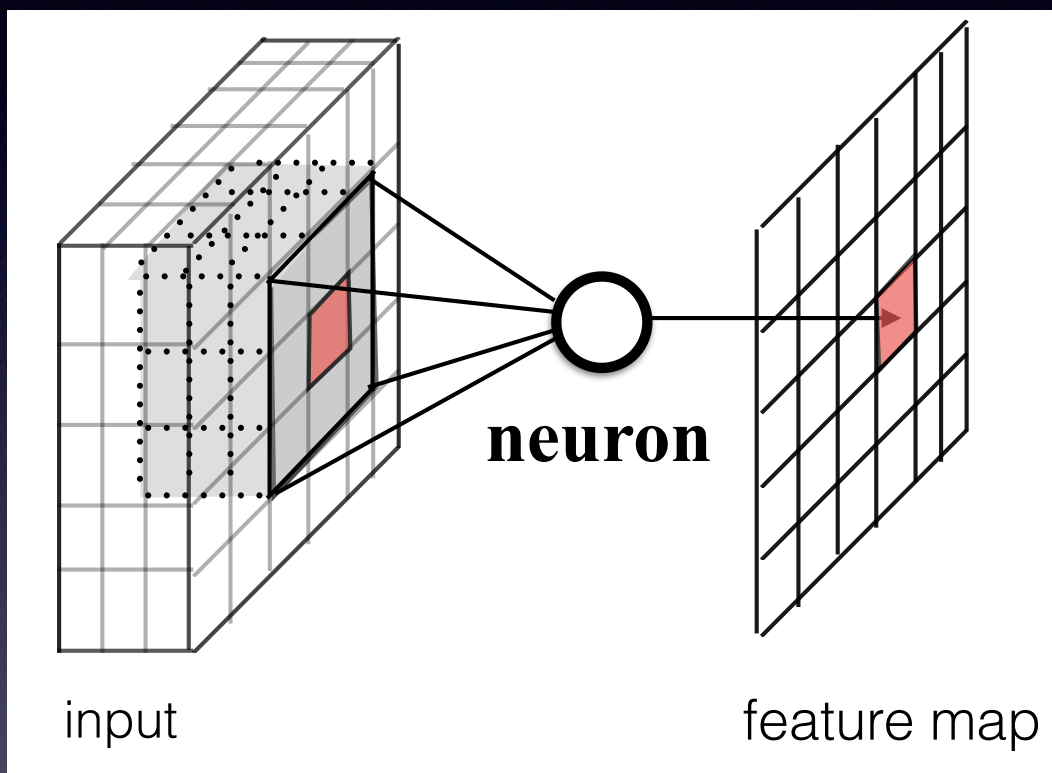


Cat?

Problem: generalization

Introduction to CNNs (III)

CNN introduce a **limitation** by forcing the network to look at only **local, translation invariant features**



$$f_{i,j}(X) = \sigma(W_i \cdot X_j + b_i),$$

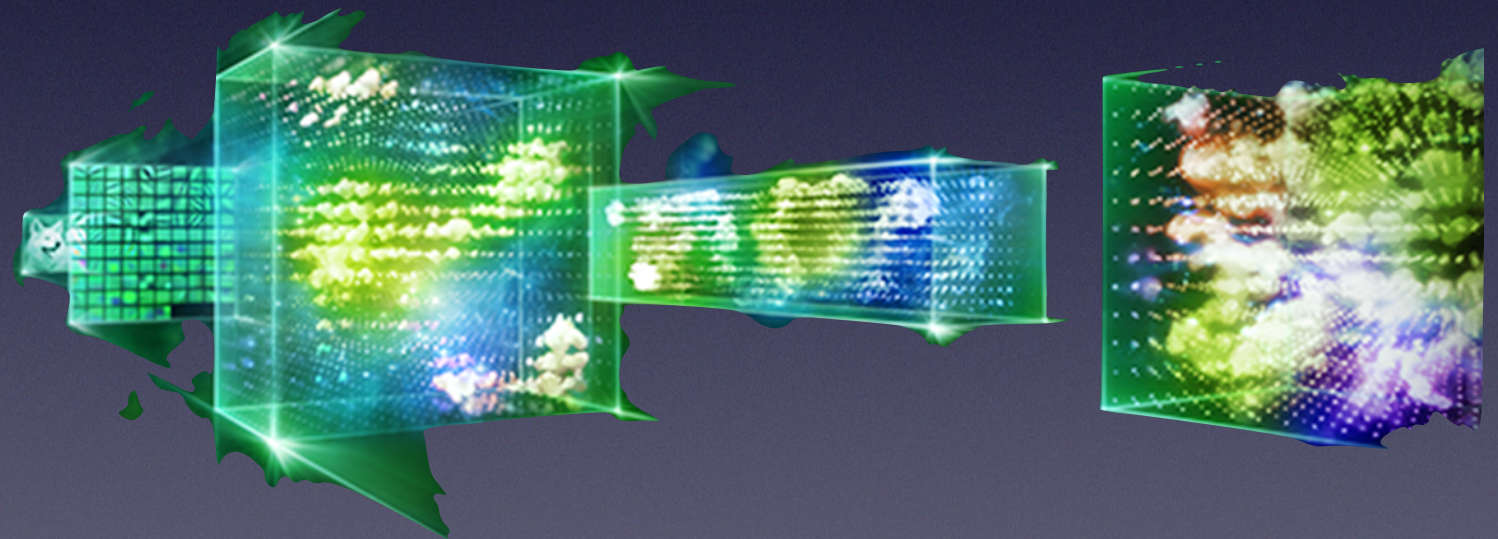
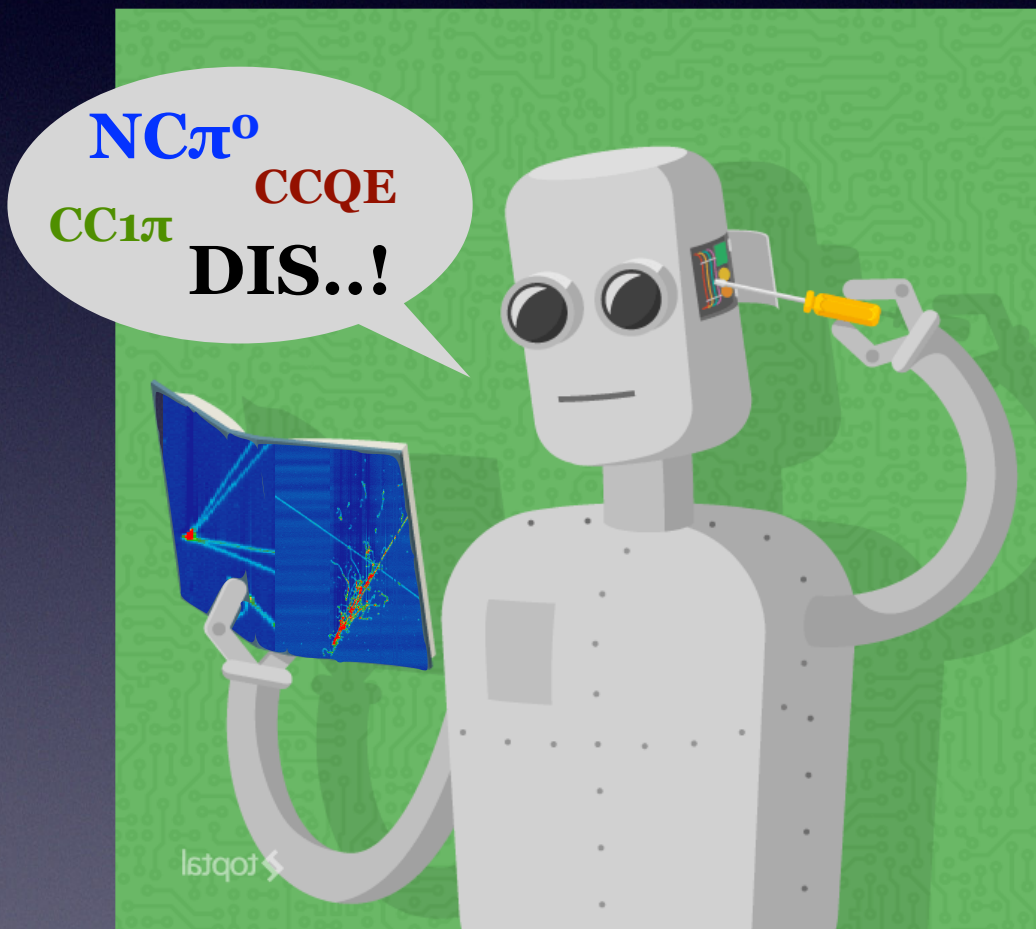
Activation of a neuron depends on the element-wise product of 3D weight tensor with 3D input data and a bias term

- Translate over 2D space to process the whole input
- Neuron **learns translation-invariant features**
- Applicable for a “homogeneous” detector like LArTPC

**Want more details?
Feel free to ask me later!**

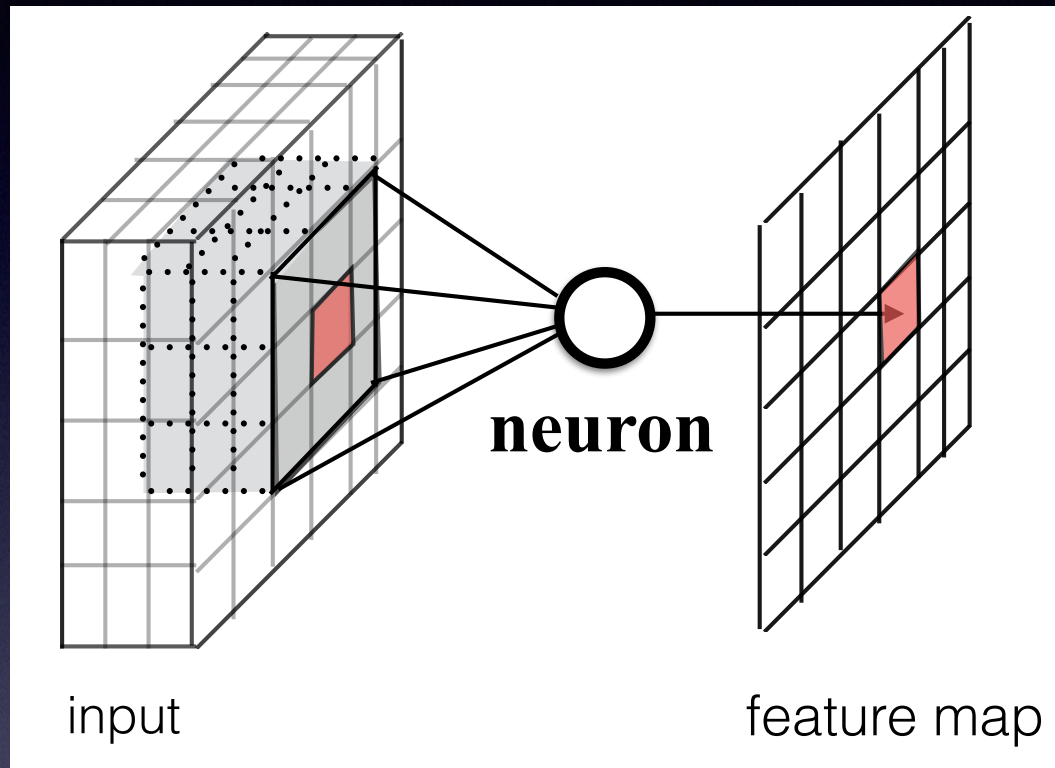
Track/Shower Pixel Labeling

~ How Does SSNet Work? ~



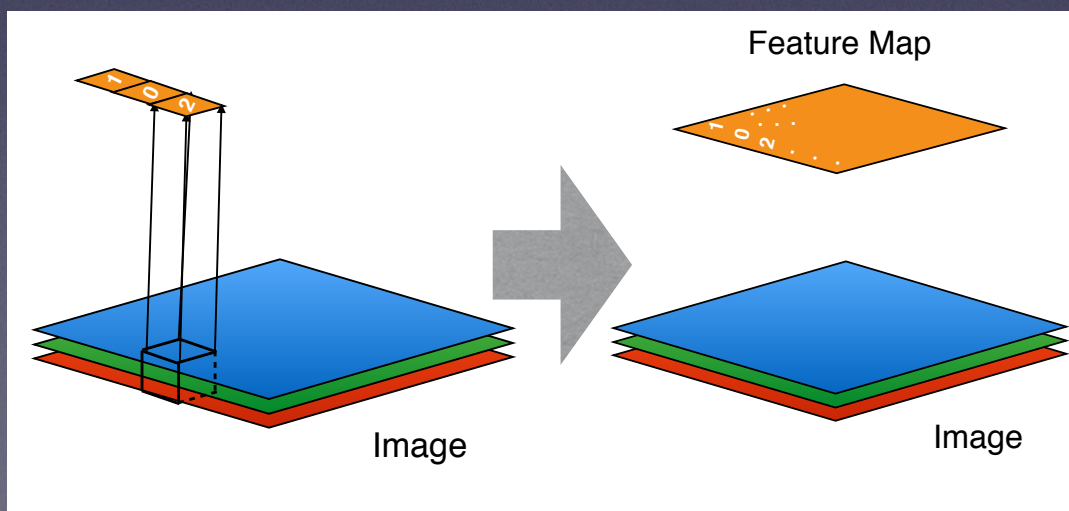
Quick Recap on CNN

CNN is a neural network formed with multiple convolution layers of neurons



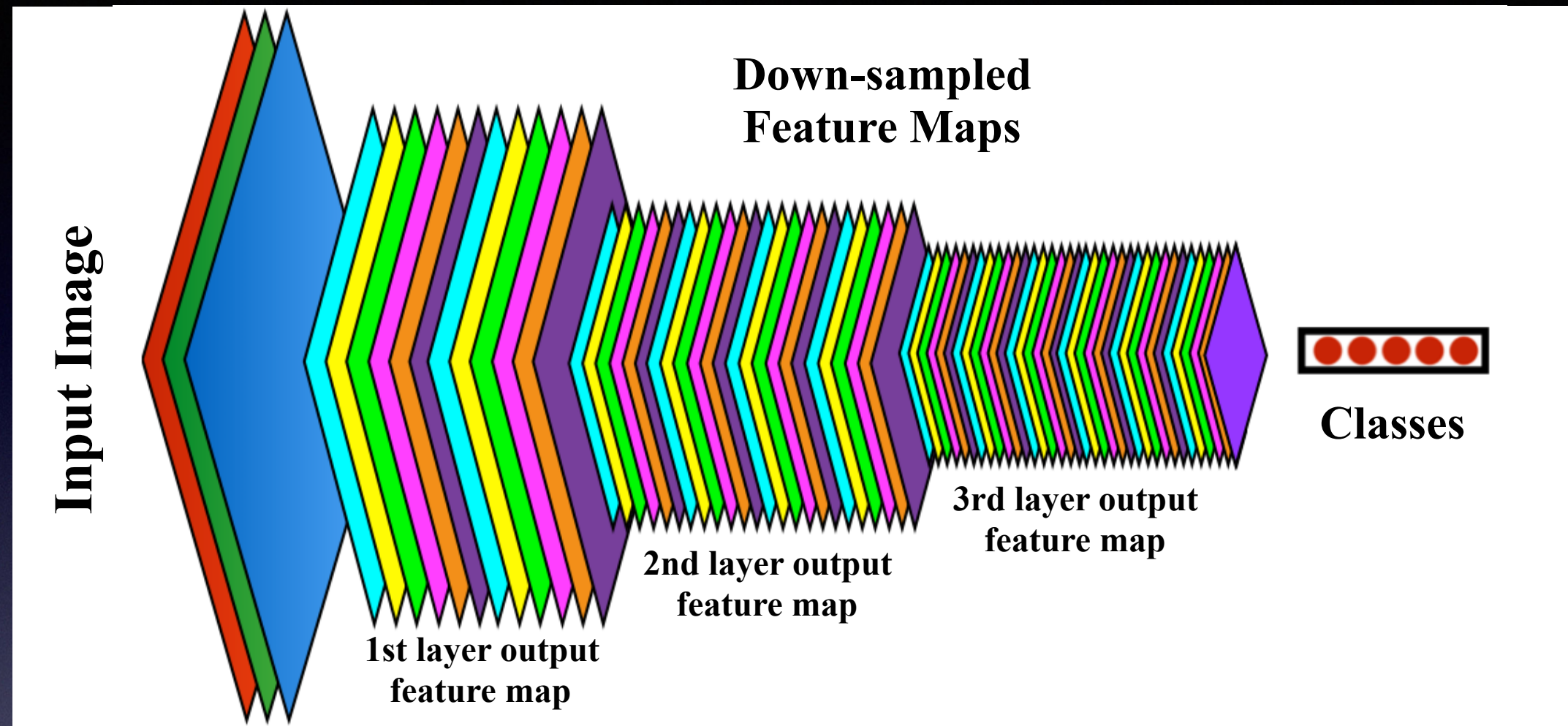
$$f_{i,j}(X) = \sigma(W_i \cdot X_j + b_i),$$

Activation of a neuron depends on the element-wise product of 3D weight tensor with 3D input data and a bias term



Each **filter** (neuron) translates over 2D space to process the whole input, producing a “*feature map*”.

Quick Recap on CNN



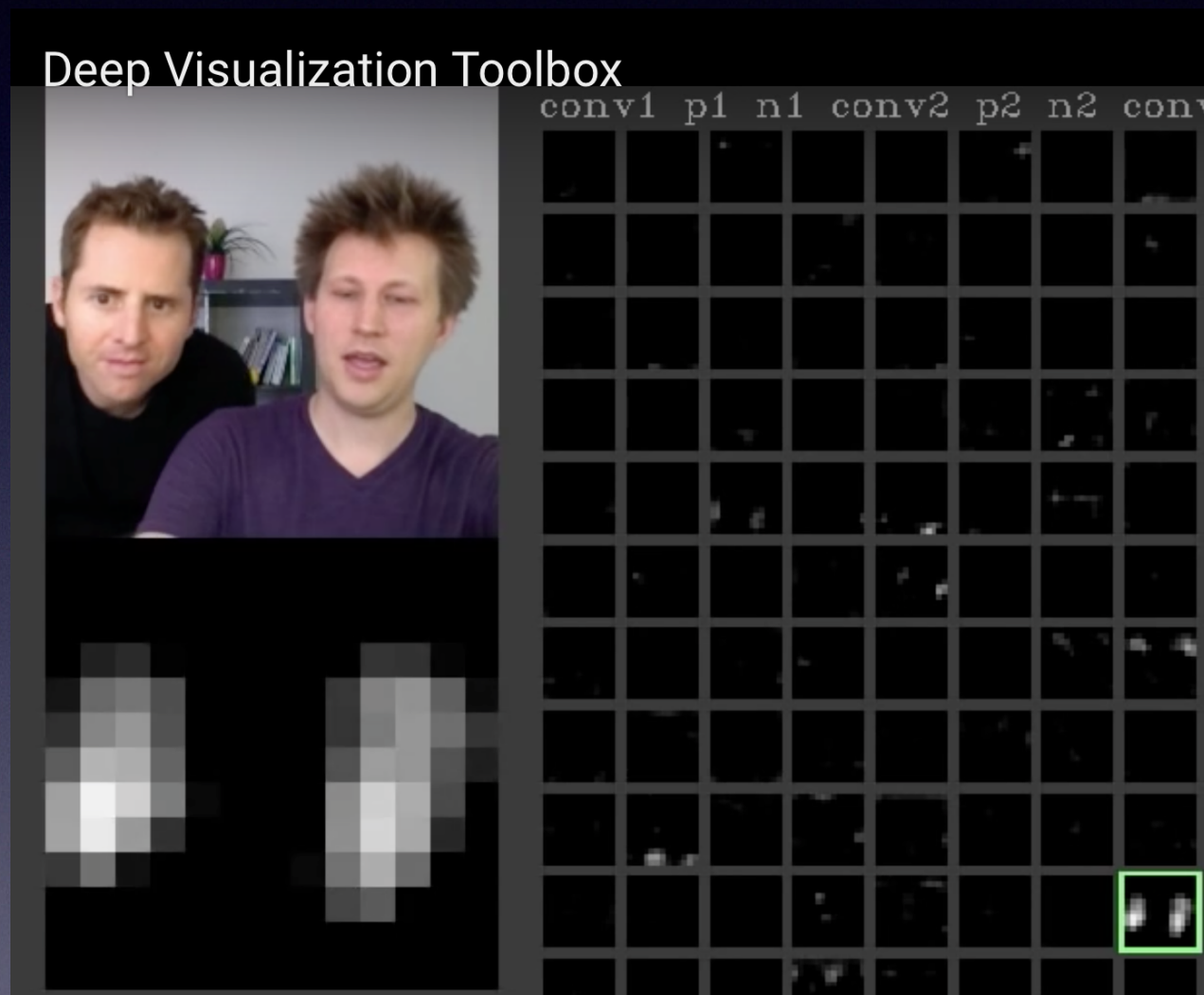
CNN for image classification

- **Goal**: provide a single label for the whole image
- **How**: transform the higher spatial resolution input (i.e. image) into a vector of image features, ultimately a 1D array of feature parameters useful for the whole image labeling, by a successful chain of convolutional and pooling operations.

Quick Recap on CNN

Feature map visualization example

- <https://www.youtube.com/watch?v=AgkfIQ4IGaM>



Neuron concerning face

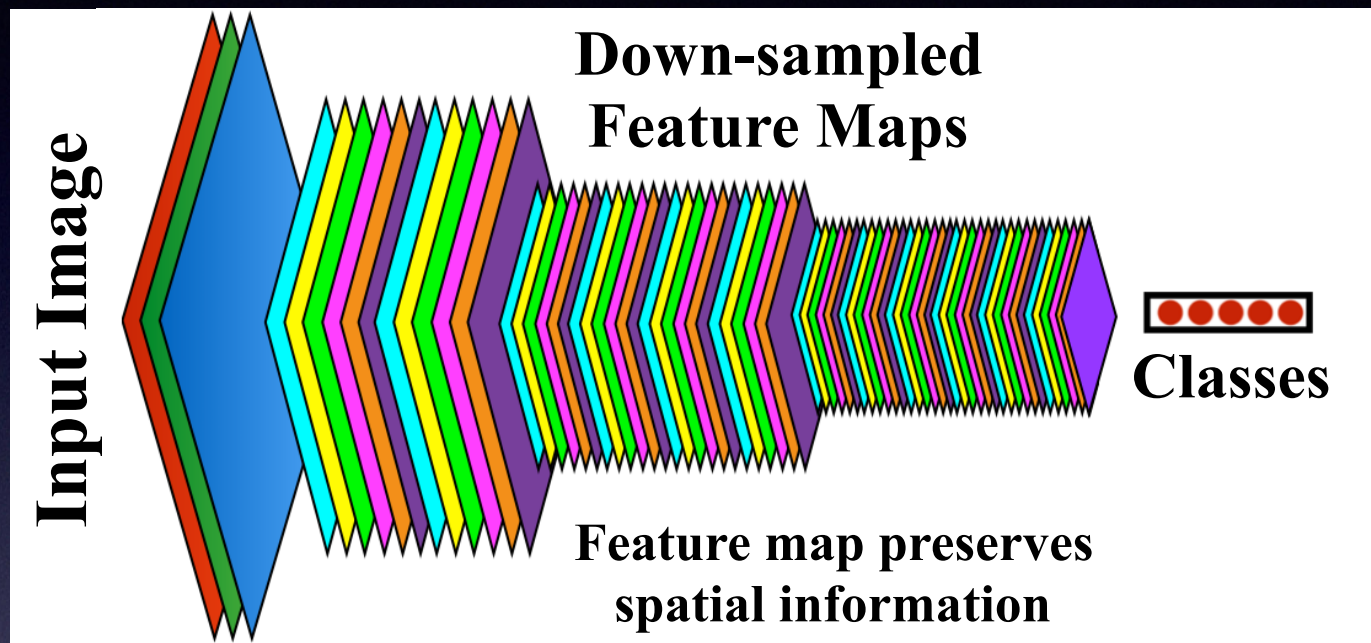


Neuron loving texts

Semantic Segmentation Network

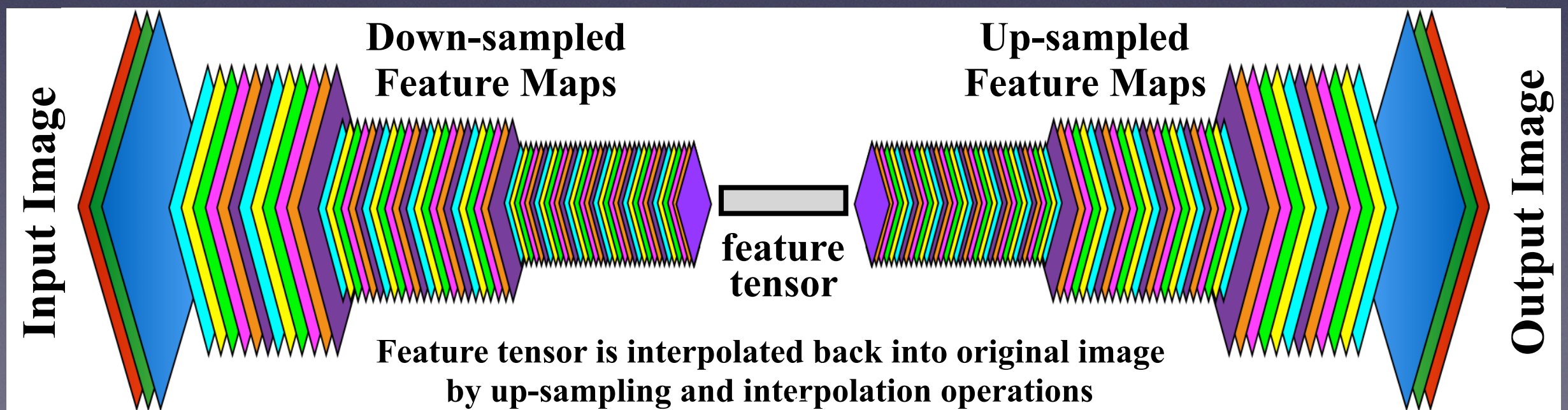
How is it different from *Image Classification*?

Example CNN for Image Classification



- Classification network reduces the whole image into final “class” 1D array
- SSNet, after extracting class feature tensor, interpolates back into original image size

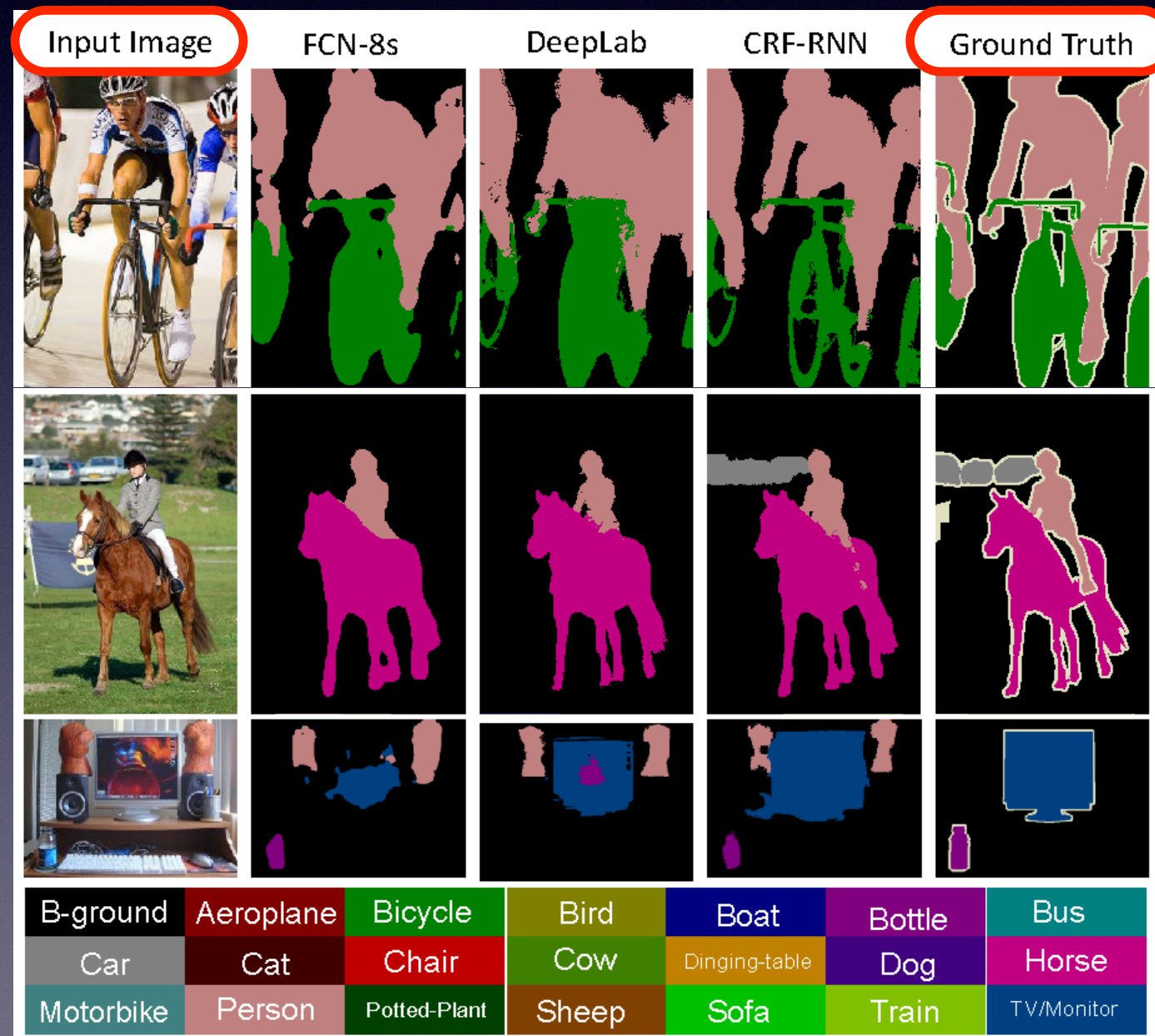
Example CNN for Semantic Segmentation



Semantic Segmentation Network

How to train SSNet?

Supervised training, like image classification
But the *labels (and errors) are pixel-wise*



Semantic Segmentation Network

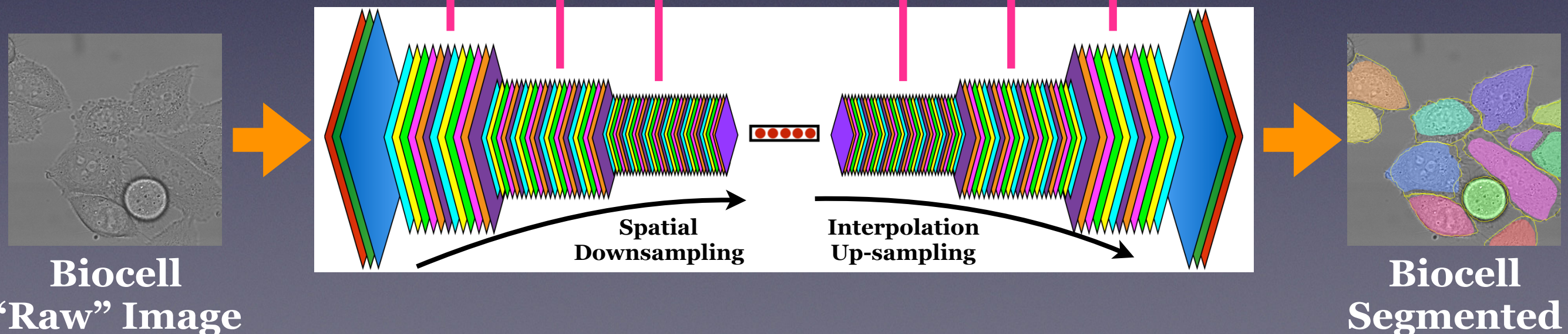


SSNet UB Analysis

U-Net + ResNet module design

- Developed for bio-medical research
 - ... to mask pixels of living cells (for automatized image analysis)
 - Designed for better spatial accuracy to get cells' boundary correct
- Use ResNet architecture for convolution layers

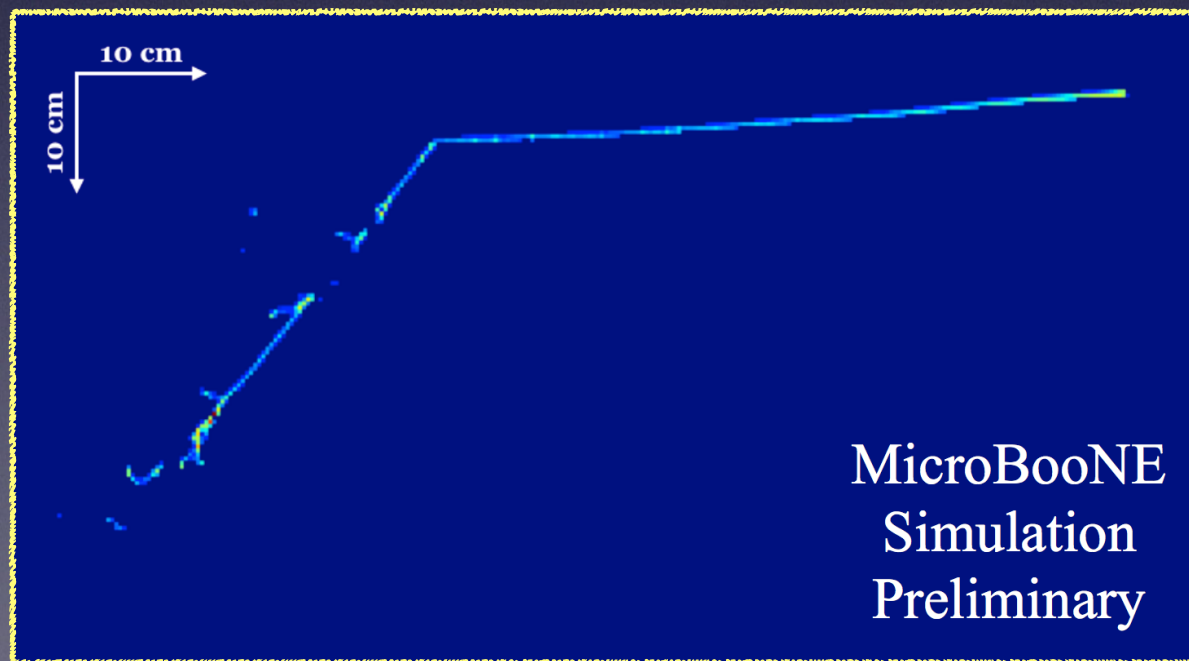
“U” shape is formed
by concatenating
feature maps



Training SSNet

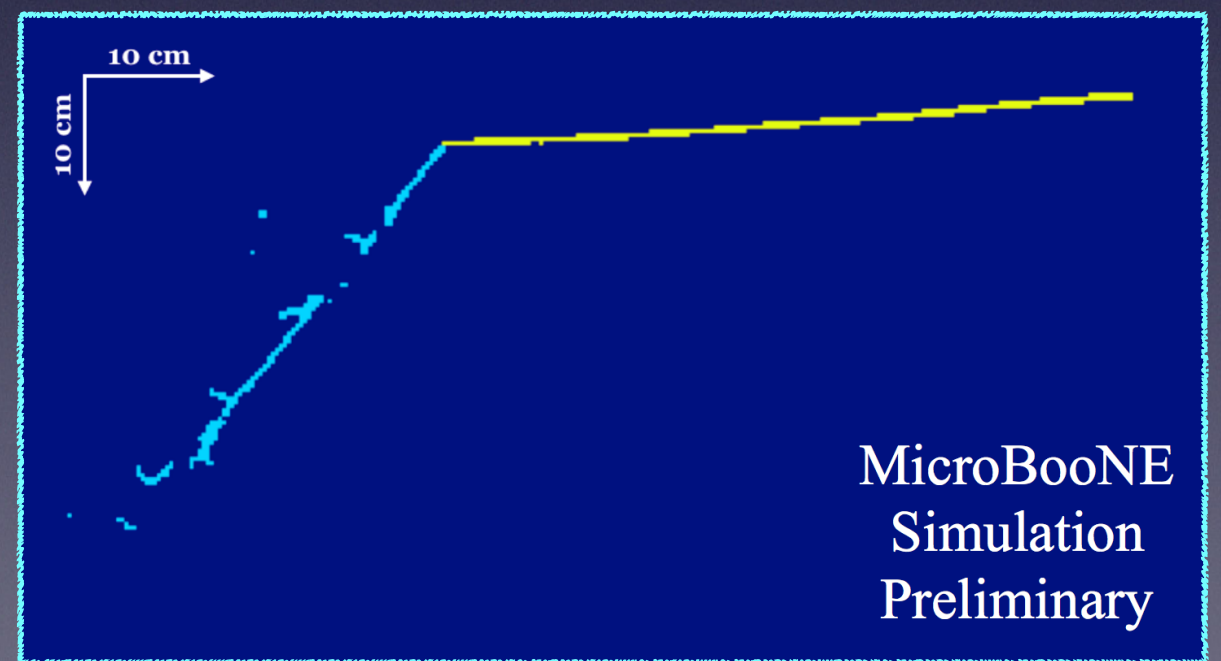
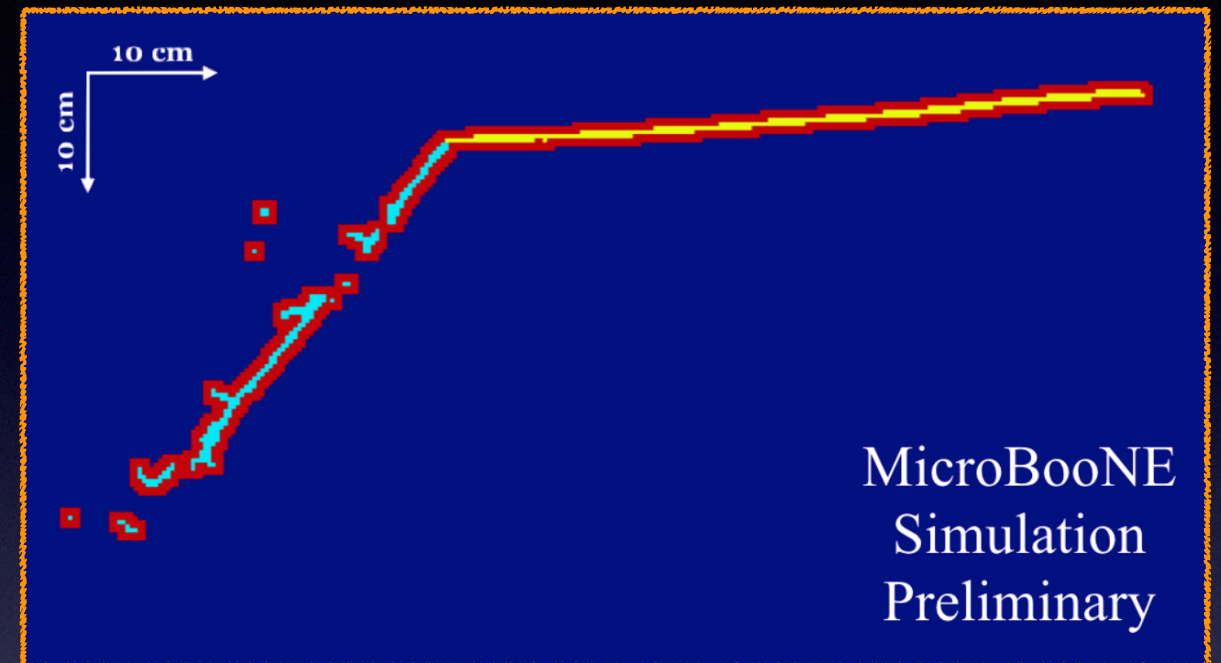
“Pixel Weight” for training

- Assign pixel-wise “weight” to penalize mistakes
- Weights inversely proportional to each type of pixel count
- Useful for LArTPC images (low information density)



Input Image

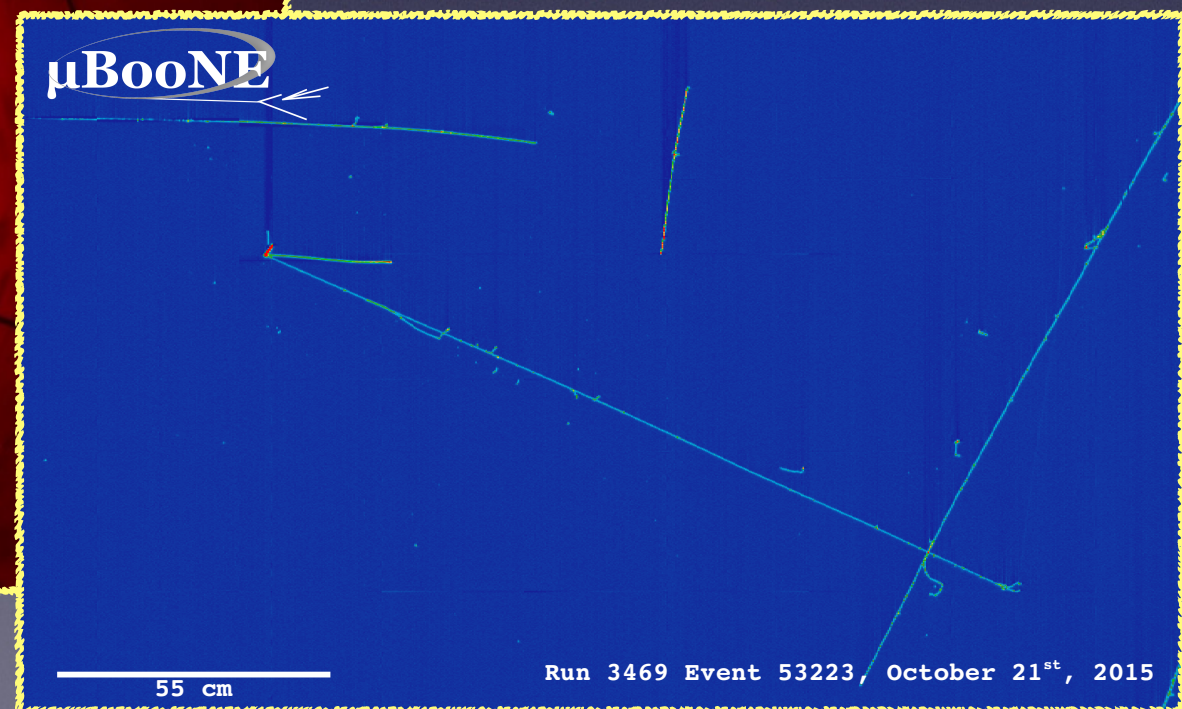
“Weight” Image (for training)



“Label” Image
(for training)



MicroBooNE LArTPC Detector Quick Guide



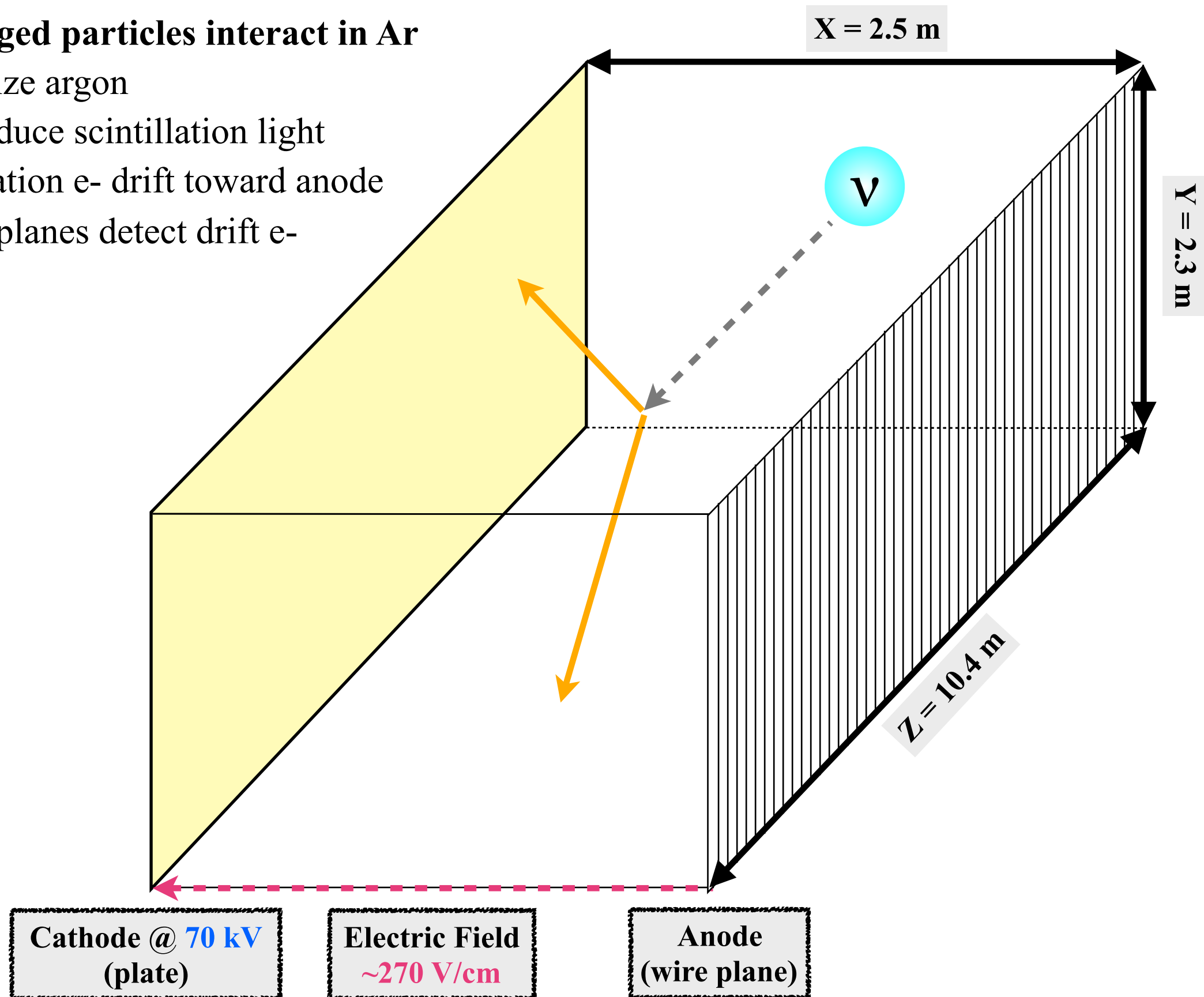
TPC Working Principle (I)

1. Charged particles interact in Ar

- Ionize argon
- Produce scintillation light

2. Ionization e- drift toward anode

3. Wire planes detect drift e-



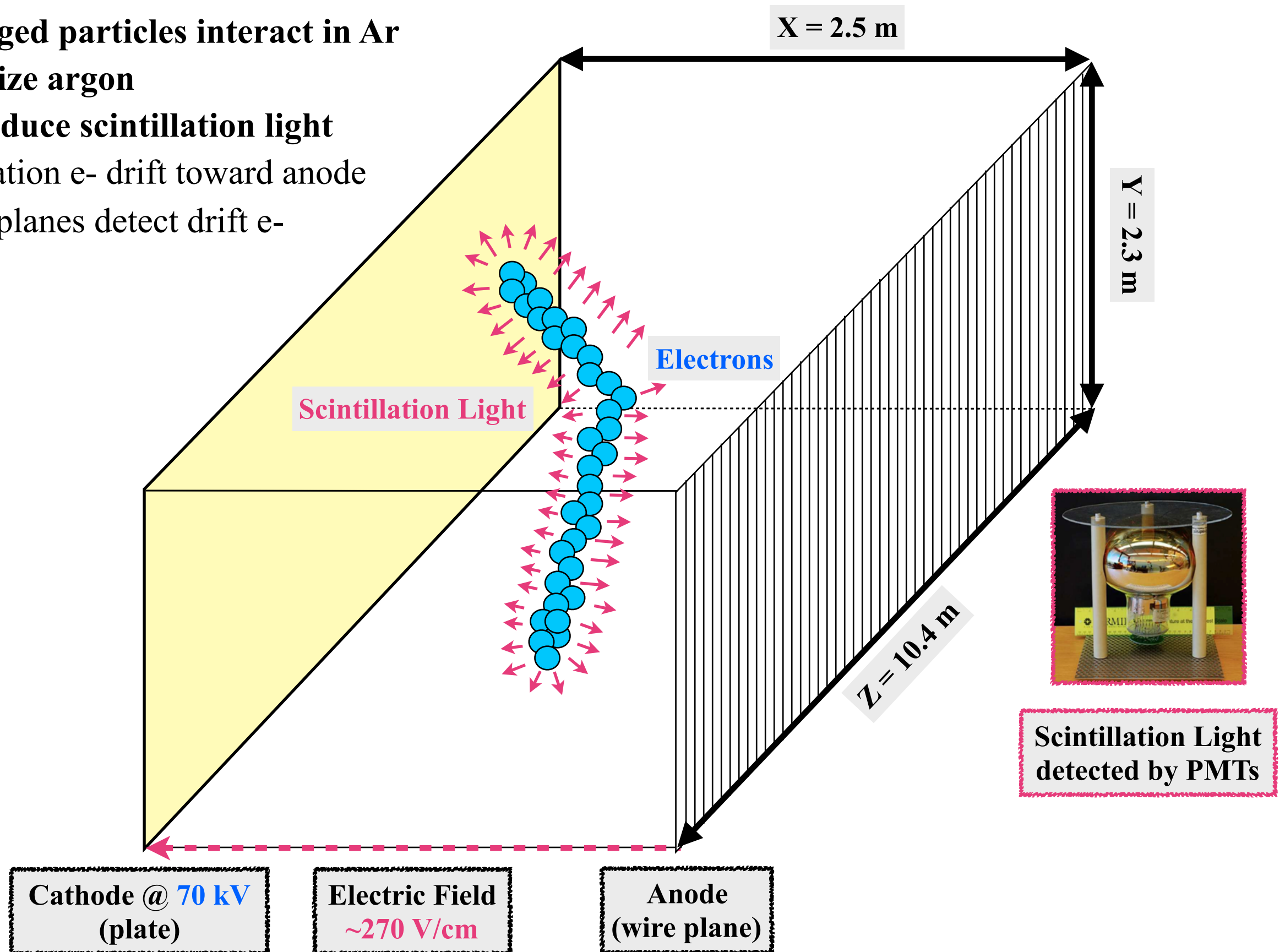
TPC Working Principle (II)

1. Charged particles interact in Ar

- Ionize argon
- Produce scintillation light

2. Ionization e- drift toward anode

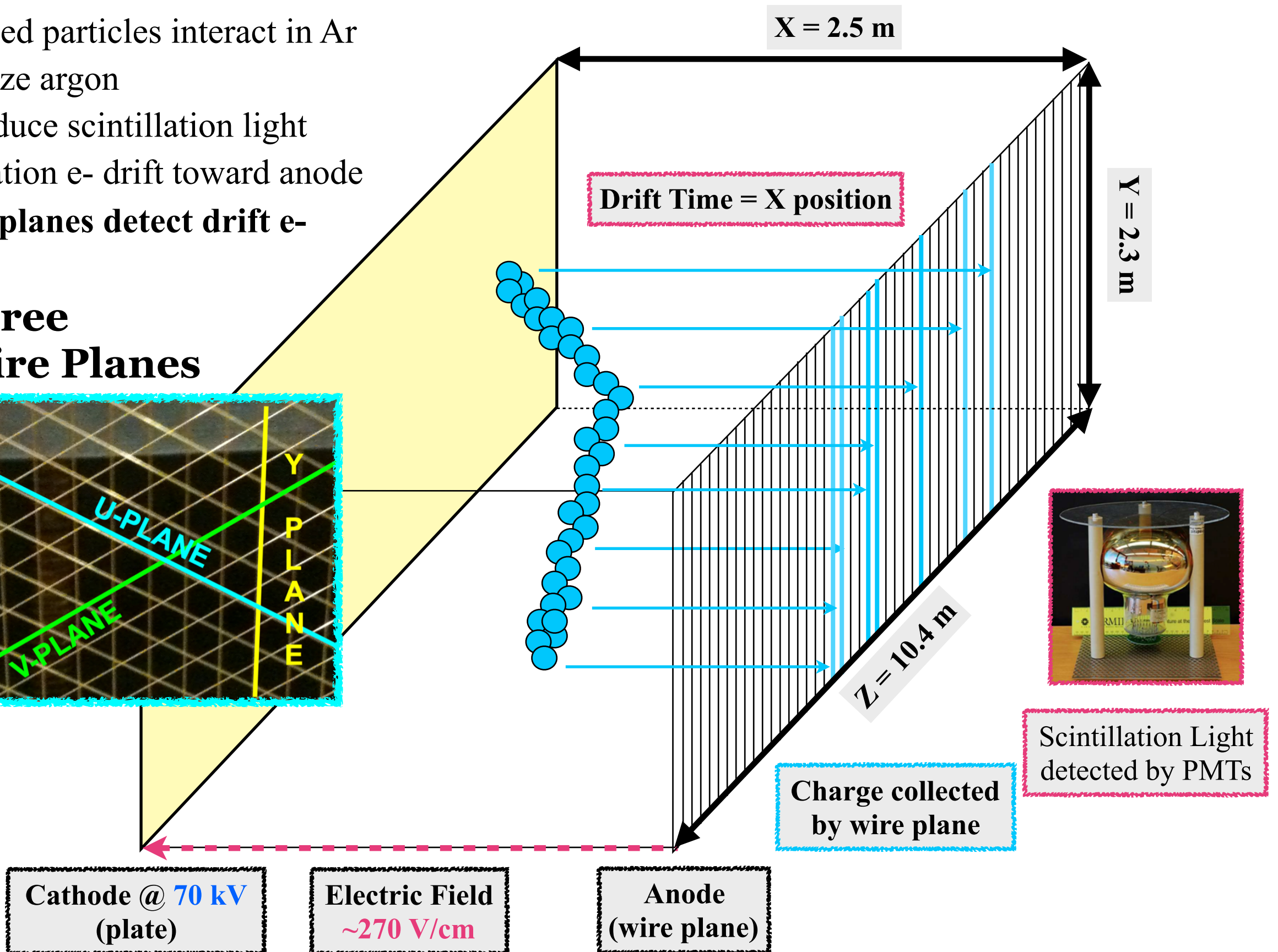
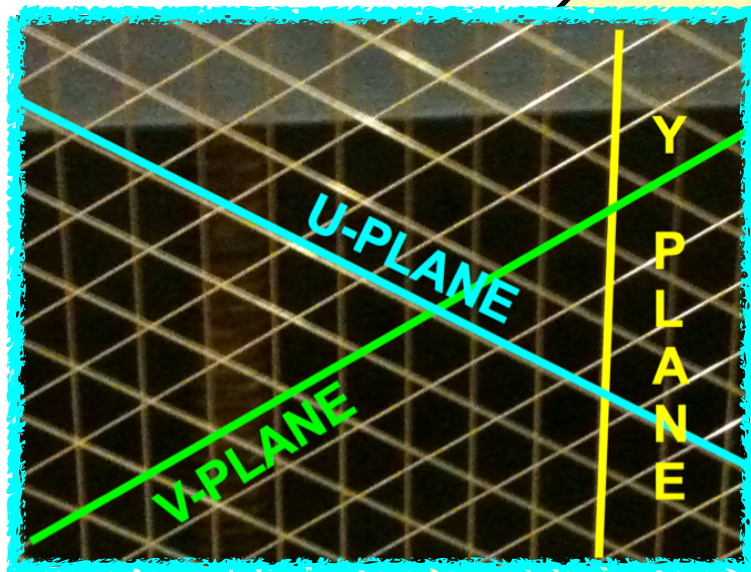
3. Wire planes detect drift e-



TPC Working Principle (IV)

1. Charged particles interact in Ar
 - Ionize argon
 - Produce scintillation light
2. Ionization e- drift toward anode
3. Wire planes detect drift e-

Three Wire Planes



MicroBooNE TPC & Cryostat



Anode Wire Plane

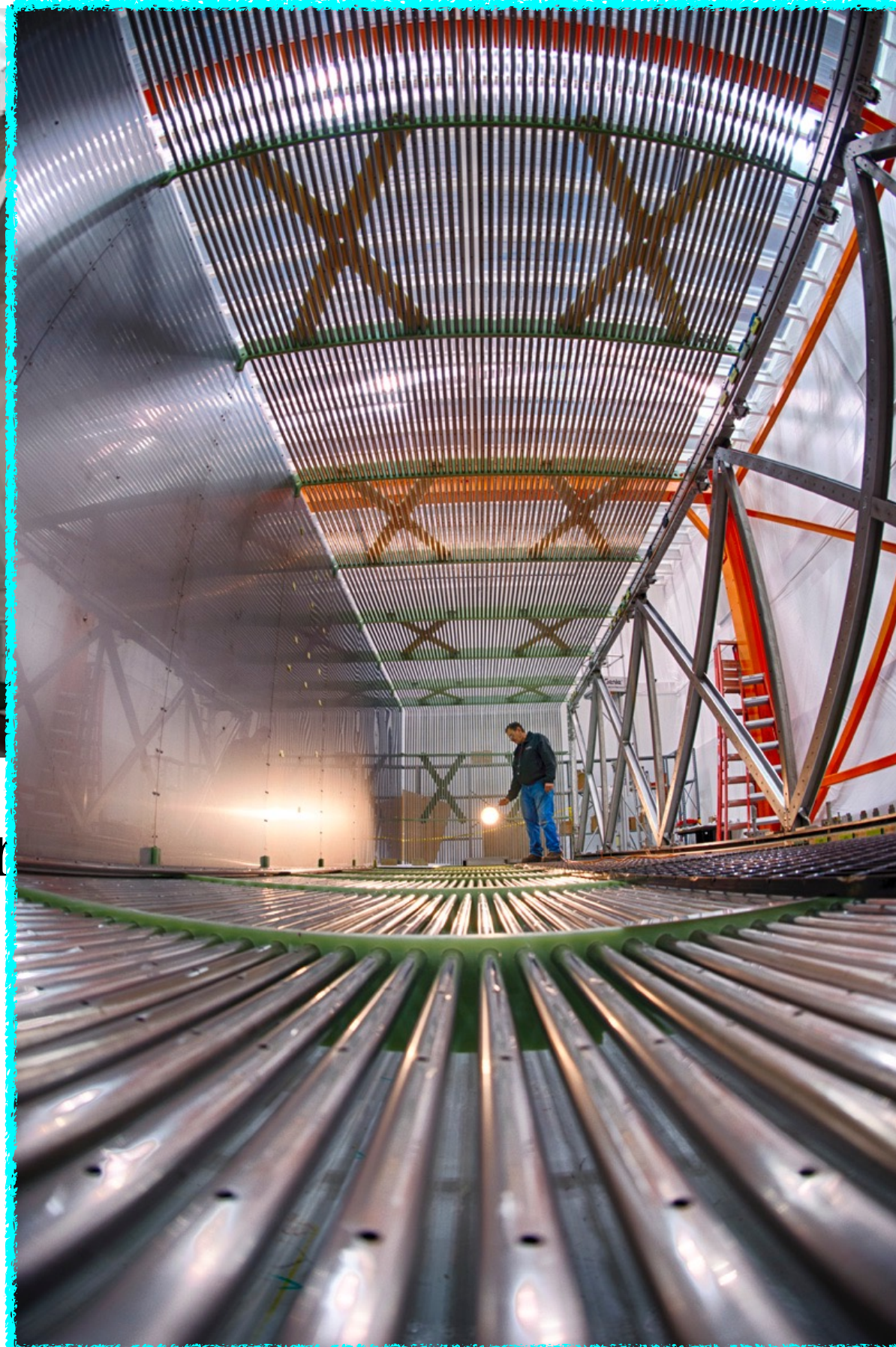


Cathode Plate

MicroBooNE TPC & Cryostat



Anode Wire



Anode Plate

MicroBooNE TPC & Cryostat

